

# WCC 310 & WCC 320 UL Plus versions

Installation instruction  
(Version 2402)

## UL MotorController



For firmware version from:

MotorController version	Main card	Motor card
U1 and U5	1.43	2.12
U2, U3 and U4	2.15	2.12

**Save this installation instruction to the end user**

The latest version of this document can always be found on our website

All dimensions are originally in metric units and converted into imperial units.  
For exact measurements please refer to documentation with metric values.

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# 1 Safety information

## 1.1 Safety

Only allow correspondingly trained, qualified and skilled personnel to carry out installation work.

Reliable operation and the avoidance of damage and hazards are only guaranteed if installation and settings are carried out carefully in accordance with these instructions.

There may be personal danger by electrically operated windows:

- the forces occurring in the automatic mode can be such that parts of the body could get crushed
- when opened, actuators (spindles) could protrude into the room

For this reason, measures have to be taken prior to starting up the actuators, which exclude the danger of injury.

For safety reasons we recommend to install opening restrictors on bottom-hung windows.

In the event that windows are subjected to rain and/or high wind loads, we recommend connecting a wind/rain sensor to the MotorController for the automatically closing of the windows.

The MotorController is to be located in a safe place, protected from the effects of fire and smoke.

The MotorController is to be surface mounted.

The MotorController is supplied by 120 V AC

The manufacturer does not assume any liability for possible damage resulting from inappropriate use.

## 1.2 120V AC

120V AC can cause death, severe injury or considerable damage to assets.

The connection of the MotorController is reserved for qualified personnel.

Disconnect all poles of the MotorController from the supply voltage prior to opening, installation or assembling.

Installation and use according to the national regulations.

## 1.3 Application

The MotorController is exclusively designed for the automatic opening and closing of windows, flaps or doors.

Always check that your system meets the valid national regulations.

Pay particular attention to the opening cross section, the opening time and opening speed.

The cable cross sections depend on the cable length and current consumption (amperage).

## 1.4 Cable routing and electrical connection

Fuse the 120VAC power supply cable separately on site.

Cable routing and connection - adhere to national regulations.

Establish the cable types, if necessary, with the local approval bodies.

Do not conceal flexible cables.

Junction box must be accessible for maintenance purposes.

Disconnect all poles of the mains voltage prior to starting maintenance work or making changes to the system.

Secure the system to prevent unintentional switching on again.

Route all low voltage cables (24VDC) separate from the power current cables.

Design cable types, lengths and cross sections in accordance with the technical information.

Cable specifications is a guide only, the overall responsibility resides with the electrical contractor on site.

Installation must be in accordance with the national electrical regulations.

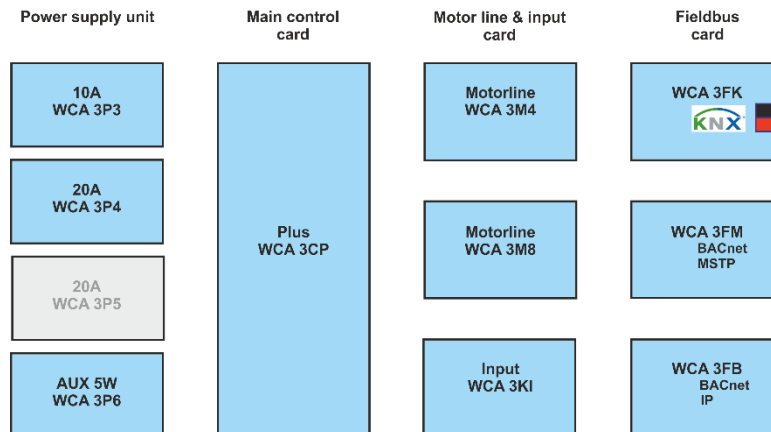
## 2 Structure of the MotorController

### Sizes & Versions

The WCC 310 and WCC 320 MotorControllers are available in two different versions namely a Standard and a Plus version. This installation instruction only deals with the Plus versions. Please see separate installation instruction for the Standard versions of WCC 310 and WCC 320.

### Cards

Each MotorController contains a power supply unit (SMPS), either a WCA 3P3 or a WCA 3P4 for the 10A or 20A version respectively, as well as a 5W auxiliary power supply. Aside from the power supply unit the Plus version also includes a main control card type WCA 3CP, which includes a touch screen for easy configuration of the MotorController. Motor line and input cards, as well as fieldbus cards, can be added to the MotorController depending on requirements.



### Selection of cards

The Main control card type WCA 3CP allows connections of 2 motor lines and 2 keypads. If more than 2 motor lines or 2 keypads are required, the necessary cards can be added.

Cards:

- WCA 3M4 motor line card, allows additional 4 motor lines.
- WCA 3M8 motor line card, allows additional 8 motor lines.
- WCA 3KI input card, allows additional 10 keypads (requires WCA 3M4 or WCA 3M8).

A fieldbus card must be added, if communication via KNX or BACnet is required.

Fieldbus cards:

- WCA 3FK fieldbus card, fieldbus interface for KNX
- WCA 3FM fieldbus card, fieldbus interface for BACnet / MSTP
- WCA 3FB fieldbus card, fieldbus interface for BACnet IP

Installation of cards may only be done when there is no power on the MotorController. Motor line and input cards are ordered together with the MotorController and mounted to the MotorController from the factory side, whereas the fieldbus cards are delivered as individual products and are to be mounted by the customer – see separate installation manual for mounting of fieldbus card.

The item no. of the MotorController specifies the type and mounting of the cards - see "Variants of MotorController" for more information

### Motor groups and motor lines

A motor group consists of one or more motor lines and all the motor lines are operated simultaneously.

The motor lines on both the main control card (WCA 3CP) and the motor line cards (WCA 3M4 or WCA 3M8) can all be configured for either a  $\pm 24V$  standard actuators or MotorLink<sup>®</sup> actuators. A motor group can contain motor lines with both  $\pm 24V$  standard actuators and MotorLink<sup>®</sup> actuators, whereas a motorline only can have  $\pm 24V$  standard or MotorLink<sup>®</sup> actuators connected.

### Adding MotorControllers

The natural ventilation installation can be expanded by adding more MotorControllers and creating a master/slave connection among them. The master/slave connection is done directly on the WSA 3CP card. The total cable length between 2 MotorControllers must not exceed 656ft.

### 3 Variants of MotorControllers

Item composing									
WCC 3	xx		P		xx	xx		Ux	
Ux = UL Std. 325 and product version number For NV Embedded® the MotorController must be version U2, U3 or U4									
Input card* 02 = No input card 12 = Input card (10 additional keypad inputs)									
Motor line card 02 = No motor line card 06 = Motor line card (4 additional lines) 10 = Motor line card (8 additional lines)									
MotorController version P = Plus									
MotorController size 10 = 10A 20 = 20A									
MotorController series 3									

\*requires a motor line card

#### 3.1 MotorController version

Number of motor lines and other functions	Cards	Item number
<b>WCC 310 versions</b>		
Plus version 2 motor lines 2 keypads / inputs	1 x WCA 3CP UL	WCC 310 P 0202 Ux
Plus version 10 motor lines 12 keypads / inputs	1 x WCA 3CP UL 1 x WCA 3M8 UL 1 x WCA 3KI	WCC 310 P 1012 Ux
<b>WCC 320 versions</b>		
Plus version 6 motor lines 12 keypads / inputs	1 x WCA 3CP UL 1 x WCA 3M4 UL 1 x WCA 3KI	WCC 320 P 0612 Ux
Plus version 10 motor lines 12 keypads / inputs	1 x WCA 3CP UL 1 x WCA 3M8 UL 1 x WCA 3KI	WCC 320 P 1012 Ux

#### 3.2 Max numbers of actuators per motor line and MotorController

The table shows the maximum number of actuators, which can be connected per motor line and MotorController depending on the type of the actuator, MotorController and connected card. The total power consumption of all the connected actuators must not exceed 10A for WCC 310 and 20A for WCC 320.

	Per motor line		Per 10A MotorController		Per 20A MotorController	
	± 24V actuators	MotorLink® actuators	± 24V actuators	MotorLink® actuators (10 Motor lines)	± 24V actuators	MotorLink® actuators (10 Motor lines)
WMU 836-1	4	4	10	10	20	20
WMU 836-2	4	2	10	10	20	20
WMU 836-3	3	3	9	9	18	18
WMU 836-4	4	4	8	8	20	20
WMU 861-1	8	4	8	8	16	16
WMU 861-2	4	2	8	8	16	16
WMU 861-3	3	3	6	6	15	15
WMU 861-4	4	4	8	8	16	16
WMU 842 / 862 / 882-1	4	4	4	4	8	8
WMU 842 / 862 / 882-2	4	2	4	4	8	8
WMU 863 / 883-1	3	3	3	3	6	6
WMU 864 / 884-1	1	1	2	2	4	4

	Per motor linie		Per 10A MotorController		Per 20A MotorController	
	± 24V actuators	MotorLink® actuators	± 24V actuators	MotorLink® actuators (10 Motor lines)	± 24V actuators	MotorLink® actuators (10 Motor lines)
WMX 503 / 504 / 523 / 526-1	8	4	20	20	40	40
WMX 503 / 504 / 523 / 526-2	8	2	20	16	40	20
WMX 503 / 504 / 523 / 526-3	6	3	18	18	39	30
WMX 503 / 504 / 523 / 526-4	8	4	20	20	40	40
WMX 803 / 804 / 823 / 826-1	4	4	10	10	20	20
WMX 803 / 804 / 823 / 826-2	4	2	10	10	20	20
WMX 803 / 804 / 823 / 826-3	3	3	9	9	18	18
WMX 803 / 804 / 823 / 826-4	4	4	8	8	20	20
WMB 801/802*	max. 4A tilsluttet på WMB					
WMB 811/812 */**	4	2	10	10	20	20

\* Do not exceed the total power consumption of the motor line

\*\* When having two locking actuators per motor line, it must be one of each type: 1 x WMB 811 and 1 x WMB 812

## 4 NV Embedded®

The WCC 310 / 320 Plus MotorControllers (version U2, U3 or U4) can be used in a NV Embedded® indoor climate solution. For further information about NV Embedded® and how to configure a NV Embedded solution please refer to the specific NV Embedded® documentation and the Appendix, which can be found on [www.windowmaster.com](http://www.windowmaster.com).

## 5 Accessories and spare parts

Accessories	
Fieldbus card with field bus interface for KNX incl. cover – sold separately, not factory mounted	WCA 3FK
Fieldbus key with field bus interface for BACnet / MSTP incl. cover - sold separately, not factory mounted	WCA 3FM
Fieldbus card with field bus interface for BACnet-IP incl. cover - sold separately, not factory mounted	WCA 3FB
Rain sensor	WLA 331
Rain/wind speed sensor	WLA 330
Rain/wind speed sensor, with pulse output	WLA 340
Weather station (only with MotorController version U4)	WOW 600
USB stick for log-data, back-up and firmware updates	WCA 304
USB stick for NV Embedded® (only with MotorController version 02, 03 or 04)	NVE Dongle
Comfort keypad for 1 window or 1 window group	WSK 110 0A0B
Comfort keypad for 2 windows or 2 window groups	WSK 120 0A0B 0A0B
Spare parts	
10A power supply unit for WCC 310	WCA 3P3
20A power supply unit for WCC 320	WCA 3P4
5W 120 AC / 24V DC	WCA 3P6
Main control card for Plus version WCC 310 / WCC 320 incl. cover	WCA 3CP UL
Motor line card with 4 motor lines incl. cover	WCA 3M4 UL
Motor line card with 8 motor lines incl. cover	WCA 3M8 UL
Input card with 10 inputs for e.g. key pads incl. cover (requires WCA 3M4 or WCA 3M8)	WCA 3KI
Plastic covers for the cards in the WCC 310 / WCC 320 Plus version	WCA 301
Fieldbus card with field bus interface for KNX incl. cover	WCA 3FK
Fieldbus card with field bus interface for BACnet / MSTP incl. cover	WCA 3FM
3.15A fuse for motorline, 10 pcs (Littelfuse 807 13150440)	WCA 308

## 6 Technical data

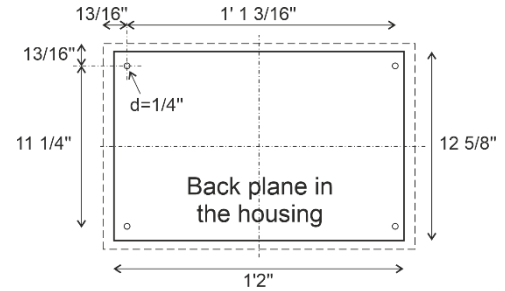
Technical data		
Output current (nominal)	WCC 310: 10A / WCC 320: 20A	
Secondary voltage	Voltage 27V DC ( $\pm 0.02\%$ ) Open circuit voltage (no load) 27.6V DC @ 20°C Ripple at max load max. 6% (3.5Vpp)	
AUX	24V DC, 0.23A	
Motor lines	WCC 310 0202: max 2, WCC 320 1012: max 10 A motor line can contain either $\pm 24V$ standard or MotorLink® actuators	
Motor groups	WCC 310 0202: max 2, WCC 320 1012: max 10 Via the touch screen motor motorlines can be connected in the same group	
Primary voltage	120V AC, 60Hz (85-264V AC, 47-63Hz)	
Power consumption	Idle consumption WCC 310: min 2W <sup>1</sup> , typ. 4.2W <sup>2</sup> WCC 320: min 2W <sup>1</sup> , typ. 5W <sup>3</sup>  1) min.: 1 MotorLink® actuator 2) min.: 20 MotorLink® actuators + rain sensor 3) min.: 40 MotorLink® actuators + rain sensor  Max: WCC 310: At max load 305W WCC 320: At max load 605W	
Leakage current	Max 1.2mA @ 240VAC	
Inrush current on primary site	70A<5ms. Max 3 x WCC 310/320 per 10 A supply group. Circuit breaker "C" characteristic.	
$\pm 24V$ change over time	min 500ms	
Cable monitoring	$\pm 24V$ standard actuators with end of line module are monitored by closed-circuit Actuators with MotorLink® are monitored by data communication	
LED message OK and fault	Green Yellow	CPU working fault
Connection cable	Actuators   Other components  Mains	flexible max AWG 10 / solide max AWG 8 Min. AWG 22, 300V, 176°F Listed / Recognized to UL 13  Min AWG 24 / max AWG 16 Listed / Recognized to UL 13  Mains must be done per relevant Electrical Code. For permanent connection (rigid or flexible 1/2" conduit or equivalent) use the supplied 1/2" adaptor in the Knockout. Use AWG 10, 12, or 14 conductors (same size).
Operating conditions	+23°F - +113°F, for indoor only, MotorController must not be covered	
Max actuator activation duration (duty cycle)	ED 40% (4min. per 10min.)	
Number of motor lines per card	WCA 3CP WCA 3M4 WCA 3M8	2 x 10A motor line for $\pm 24V$ standard or MotorLink® actuators 4 x 10A motor line for $\pm 24V$ standard or MotorLink® actuators 8 x 10A motor line for $\pm 24V$ standard or MotorLink® actuators
Material	Metal housing for surface mounting	
Colour	White (RAL 9010)	
Size	1' 2" x 1' 5/8" x 3" (HxWxD)	
Weight	WCC 310: 8.8 lbs - WCC 320: 10.6 lbs	
Protection class	IP 20	
Certification	UL 325 and CSA C22.2 no 247-14 approved	
Delivery	MotorController	
Note	We reserve the right to make technical changes	



## 7 Mounting

The MotorController is fixed to the wall through the  $\varnothing 1/4''$  holes in the back plane of the housing.

The MotorController is to be located in a safe place, protected from the effects of fire and smoke.



## 8 Installation

### 8.1 Cable routing

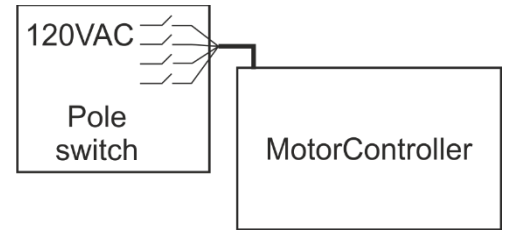
See also chapter 8 "Cable dimensioning" in this instruction.

However, this has to be agreed with the Engineer.

Do not reduce the cable cross sections specified in the cable lengths table.

All cables of the control (except the mains supply cable) carry 24V DC and have to be routed separate from the mains supply cable.

Adhere to the pertinent national and local regulations when routing the cables.



### 8.2 Cables into housing

All connection terminals (except the mains terminals) are of the plug-in type.

Connect the connection cables in accordance with the terminal plan. Ensure that the connections are made correctly.

Incorrect cable clamping, mixing up numbers or colours could lead to malfunctions of the control MotorController or of the external components.

Ensure that the electrical cables are always routed according to the valid national and local regulations.

### 8.3 Connection of safety earth wire and 120V AC

See chapter 10 'Description of cards', for further description.

### 8.4 Installation of the ventilation keypad

Ensure that the ventilation buttons are visible and well accessible. Do not install behind protruding walls, door MotorControllers or hidden by the building structure.

### 8.5 Assembly instructions

**Always have assembly, installation, repair and maintenance of ventilation systems carried out by qualified personnel trained for this purpose.**

#### Rules to be adhered to for setting up and installation

The following safety relevant rules have to be adhered to when planning the use of a ventilation system and its set-up and installation:

- The Provincial Building Ordinance of the provinces

#### Accident prevention regulations

Adhere to the general accident prevention regulations (APR), the APR for power operated windows and doors, and the installation rules in your country.

#### CAUTION:

Live components are directly accessible after opening the system housing.

Prior to inserting / removing cards disconnect to the MotorController from the mains supply.

- adhere to the installation instructions and your local energy providers
- select the place of installation such that free access is guaranteed for maintenance purposes
- select cables according to regulations in this instruction - take the calculation of the actuators supply cable lengths into account when laying the cables
- connect the cables in accordance with the drawings provided by the manufacturer
- route the cables in the building according to the regulations in this instruction
- check all system functions

## 9 Cable dimensioning

### 9.1 Max. cable Length

Maximum permissible cable length from the MotorController to the actuators taking into account the cable cross-section is shown in the following tables for “± 24V standard actuators“, “MotorLink® actuators“.

#### 9.1.1 Formula for the calculation of the maximum actuator cable length

Max. cable length =  $\frac{\text{permissible voltage drop } 2V \text{ (UL)} \times \text{conductivity of copper(56)} \times \text{cable cross section in mm}^2 \text{ (a)}}{\text{max. actuator current total in amps (I)} \times 2}$

For both ±24V standard actuators and actuators with MotorLink® the cable must not be less than AWG 18 (cable cross section 0.82mm²) regardless of the result of above formula.

**Maximum actuator cable length:** Always measured from the Motorcontroller to the last junction box + actuator cable

**Permissible max. voltage drop in the line:** 2 Volt

**Actuating current:** Sum of all actuator power consumption per motor line

**Note:** do not use the PE wire / green/yellow wire in the actuator cable!

#### Example

Max actuator cable length with AWG 18 (cable cross section 0.82mm²) and actuator current 2A:  $(2 \times 56 \times 0.82) : (2 \times 2) = \underline{23m}$  (76 ft)

#### 9.1.2 Max cable length – ±24V standard actuators

The actuator supply cable must have 2 wires. If monitoring is desired use min. 3: 2 wires current carrying / 1 wire for monitoring.

±24V standard actuators				
Do not use the PE wire / green/yellow wire!				
cable cross section [a] Total actuator current [I]	AWG 18 (3 wire 0.82 mm²)	AWG 16 (3 wire 1.31 mm²)	AWG 14 (3 wire 2.08 mm²)	AWG 12 (3 wire 3.31 mm²)
1A	151 ft	240 ft	382 ft	608 ft
2A	76 ft	120 ft	191 ft	304 ft
3A	50 ft	80 ft	127 ft	203 ft
4A	38 ft	60 ft	96 ft	152 ft
5A	30 ft	48 ft	76 ft	122 ft
6A	25 ft	40 ft	64 ft	101 ft
7A	22 ft	34 ft	55 ft	87 ft
8A	19 ft	30 ft	48 ft	76 ft
9A	17 ft	27 ft	42 ft	68 ft
10A	15 ft	24 ft	38 ft	61 ft
20A			19 ft	30 ft

### 9.1.3 Max cable length – actuators with MotorLink®

The actuator supply cable must have 3 wires: 2 wires current carrying / 1 wire for communication.

When using actuators with MotorLink® the max cable length is 164ft regardless of the result of the above mentioned formula.

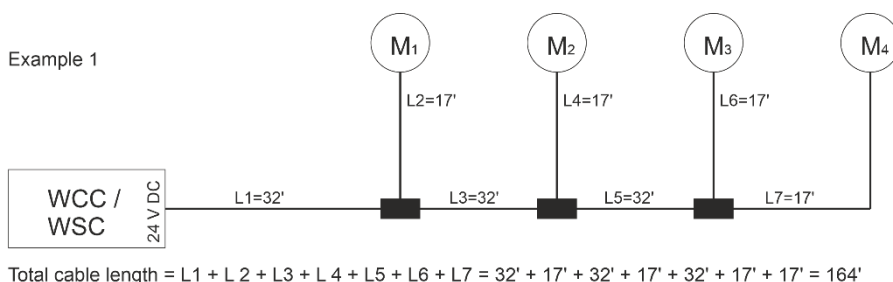
Actuators with MotorLink®				
Do not use the PE wire / green/yellow wire!				
cable cross section [a] Total actuator current [I]	AWG 18 (3 wire 0.82 mm²)	AWG 16 (3 wire 1.31 mm²)	AWG 14 (3 wire 2.08 mm²)	AWG 12 (3 wire 3.31 mm²)
1A	151 ft	164 ft		
2A	76 ft	120 ft	164 ft	
3A	50 ft	80 ft	127 ft	164 ft
4A	38 ft	60 ft	96 ft	152 ft
5A	30 ft	48 ft	76 ft	122 ft
6A	25 ft	40 ft	64 ft	101 ft
7A	22 ft	34 ft	55 ft	87 ft
8A	19 ft	30 ft	48 ft	76 ft
9A	17 ft	27 ft	42 ft	68 ft
10A	15 ft	24 ft	38 ft	61 ft
20A			19 ft	30 ft

#### Definition of total cable length

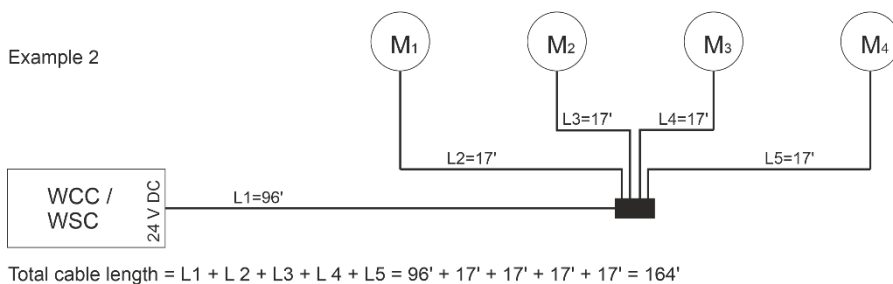
The total cable length is defined as the sum of all cables from the MotorController output to the last actuator. Including the cable mounted on the actuator.

For example, in case of 4 actuators with 17' cable each, the remaining cable length is 96'.

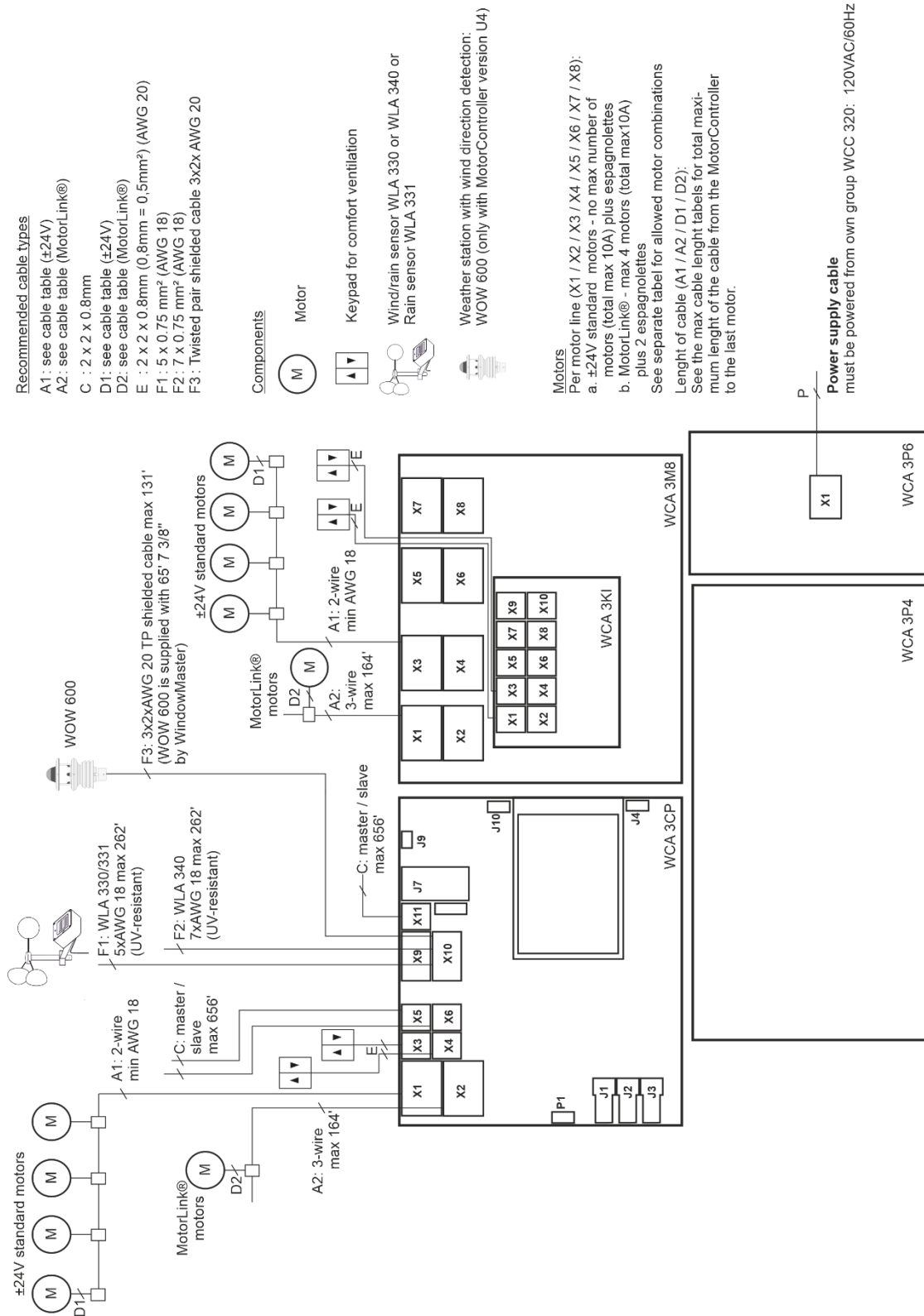
Example 1



Example 2



## 10 Cable plan for connection to WCC 310 / 320 Plus version



The above plan shows a WCC 320 MotorController

## 11 Description of cards and mains connection

Each MotorController includes a power supply unit (SMPS), an auxiliary power supply (AUX) and a main control card. Motor line can input cards for additional motor lines and inputs (e.g. for key pads) as well as a field bus card can be added when necessary.

The size of the power supply unit determines the number and/or types of actuators, which can be connected to the MotorController. See table with overview of max number of allowed actuators per motor line/MotorController (chapter 3.2).

### 11.1 WCC connection to mains and power supply units – WCA 3P3, WCA 3P4 and WCA 3P6

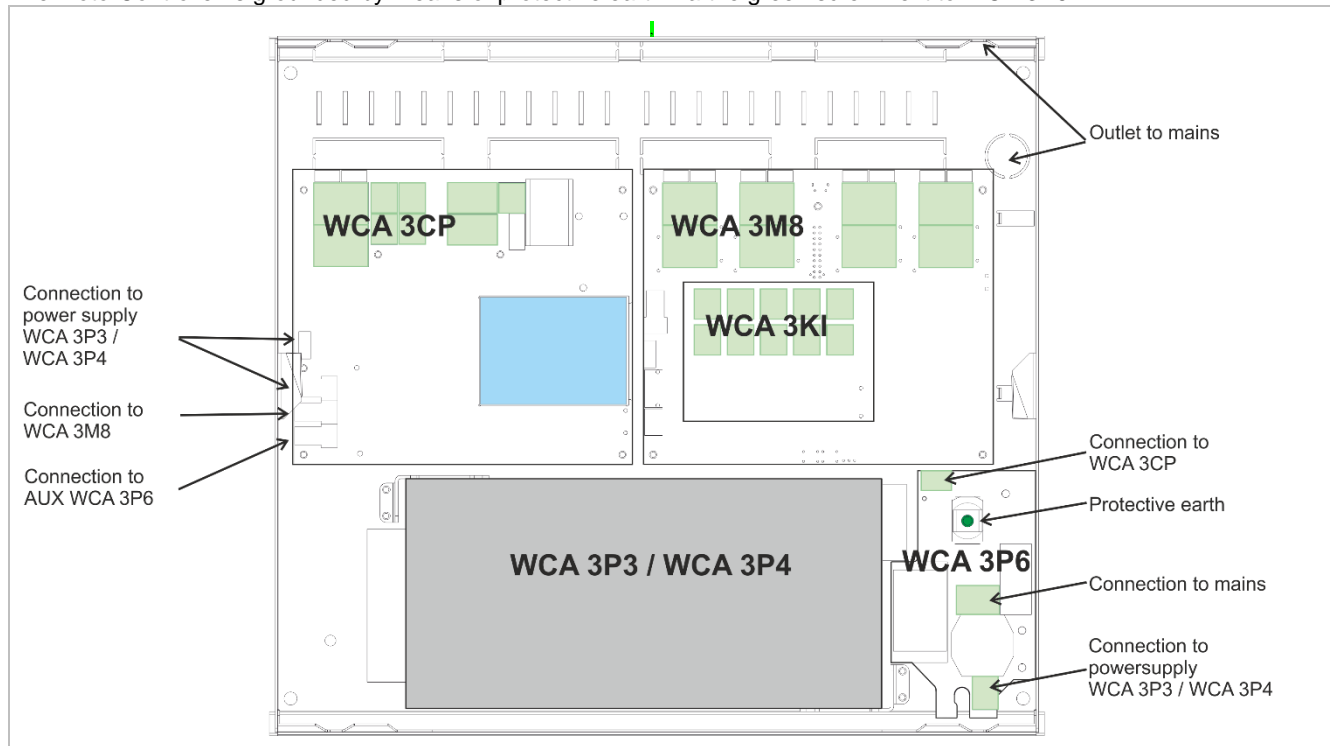
The MotorController WCC 310 is supplied with a 305W SMPS power supply – WCA 3P3.

The MotorController WCC 320 is supplied with a 605W SMPS power supply – WCA 3P4.

The power supply is, regardless of size, placed in the bottom of the MotorController beneath the motor line and input card. An AUX – WCA 3P6 – to which mains is connected, is located to the right of the power supply.

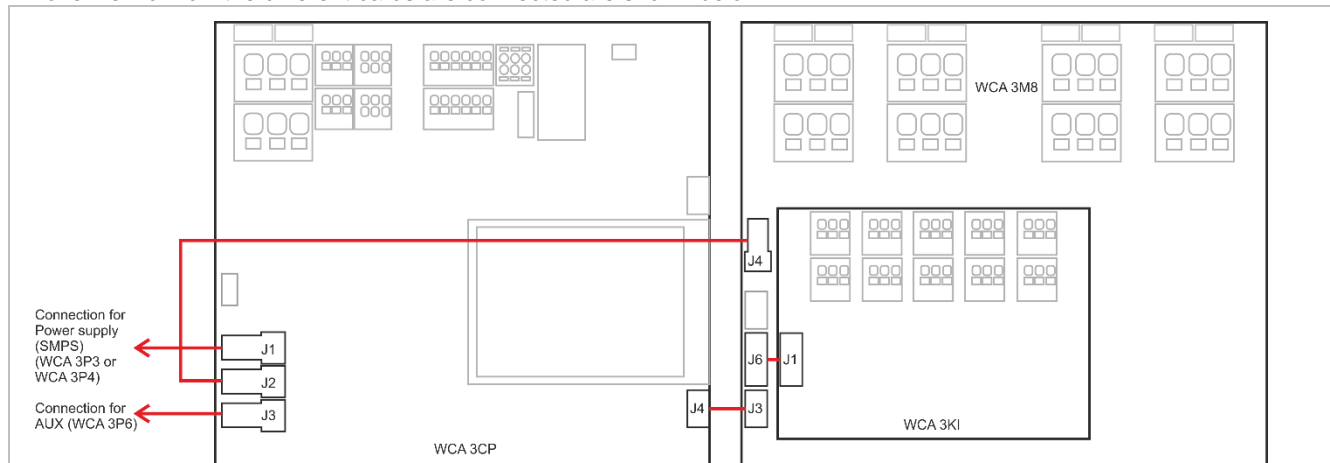
Outlet to mains is in the top right of the MotorController.

The MotorController is grounded by means of protective earth via the green screw next to WCA 3P6.



### 11.2 Connections between cards

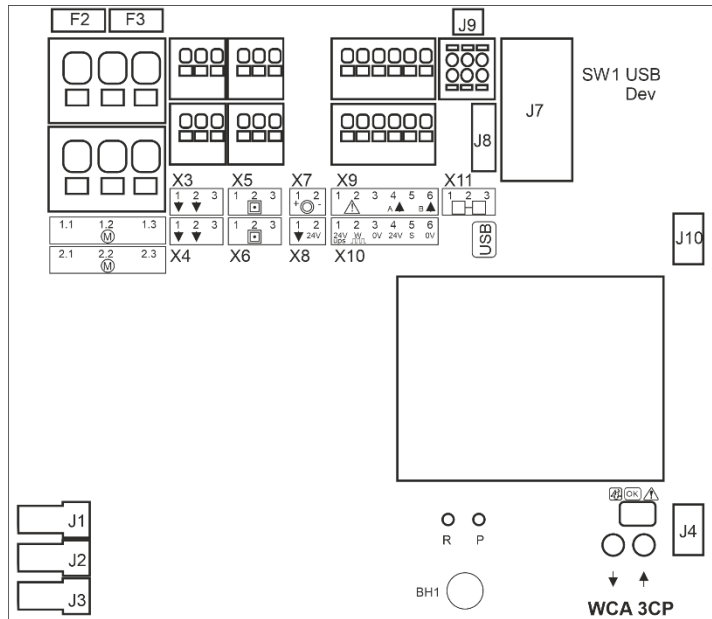
An overview of how the different cards are connected are shown below.



## 11.3 Main control card WCA 3CP – Plus Version

Each WCA 3CP contains the following:

- 2 motor lines for  $\pm 24V$  standard or Motorlink® actuators
- 2 input for keypads for comfort ventilation
- Input for weather station incl. wind direction (WLA 330 / 331 / 340 / WOW 600)
- Input for master / slave connection (WSK-Link™)
- connection of power supply
- connection to AUX
- Power for motor line card
- Connection for motor line card
- Two connections for Ethernet
- Connection for USB host and USB device
- Connection for fieldbus card
- Touch screen for configuration, commissioning and maintenance



1.1 24V / 0V	} Motorline	X11 11.1 24V IN	} WSK-Link™ Slave
1.2 Cable monitoring / MotorLink®		11.2 Comm.	
1.3 0V / 24V		11.3 0V IN	
2.1 24V / 0V	} Motorline	F2 Fuse 3.15A	
2.2 Cable monitoring / MotorLink®		F3 Fuse 3.15A	
2.3 0V / 24V			
3.1 Open 1.1	} Comfort key pad #1	J1 Power from power supply	
3.2 Close 1.2		J2 Power to motor line card (WCA 3M8)	
3.3 GND / 0V		J3 Connection to AUX	
4.1 Open 2.1	} Comfort key pad #2	J4 Connection for motor line card (WCA 3M8)	
4.2 Close 2.2		J7 2 x ethernet	
4.3 GND / 0V		J8 USB host	
5.1 24V	} WSK-Link™ Master/Slave	J9 USB device	
5.2 Comm.		J10 Connection for fieldbus card	
5.3 0V			
6.1 24V	} WSK-Link™ Master/Slave	P1 Control for power supply	
6.2 Comm.		R / P Reset / Programming	
6.3 0V		↓ ↑ Close and open all windows	
7.1 +	} Only available on WSC 310 / 320	BH1 VBAT, back-up battery for CPU and system clock	
7.2 -			
8.1 +	} Only available on WSC 310 / 320		
8.2 -			
9.1 Fault	} Output		
9.2 Fault			
9.3 Output A			
9.4 Output A			
9.5 Output B			
9.6 Output B			
10.1 24V UPS	} Weather station with wind direction		
10.2 Wind speed			
10.3 GND / 0V			
10.4 24V			
10.5 Rain			
10.6 GND / 0V			

### S1 X1 / X2

The WCA 3CP card has 2 motor lines (X1 and X2) for connection of  $\pm 24V$  standard or MotorLink® actuators.

#### $\pm 24V$ standard actuators

1.1 24V / 0V	2.1 24V / 0V
1.2	2.2
1.3 0V / 24V	1.3 0V / 24V

#### MotorLink® actuator

1.1 0V	2.1 0V
1.2 Communication	2.2 Communication
1.3 24V	2.3 24V

The number of actuators per motor line depends on the actuator type, the total power consumption of actuators connected to a motor line can max be 4A and the total max power consumption for both motor lines must not exceed 10A or 20A depending on MotorController type.

Besides actuators, also locking actuators (espagnolettes actuators) type WMB 801/802 and WMB 811/812 can be connected. The power consumption of the locking actuators are not to be included in the 10A / 20A as actuators and locking actuators do not run at the same time.

All actuators on the same motor line will run/be operated simultaneously.  
All actuators on the same motor line must be of the same type.

Connection / cable diameter: flexible max AWG 10 / solid max AWG 8.  
Cable length: see the chapter "Cable dimensioning".

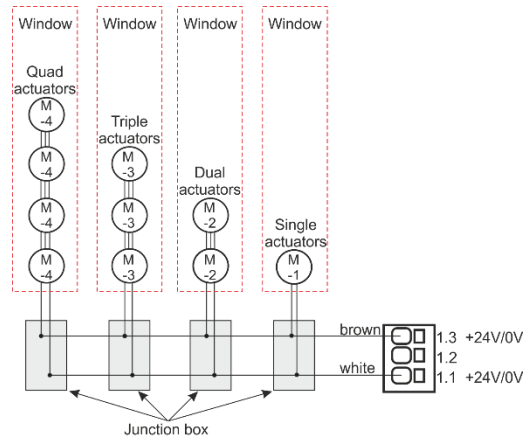
Motor lines X1 and X2 can be synchronized, so they run as a single motor line e.g. if more than 4 motors are installed on one window. Synchronization of motor lines requires FW 2.15.

### Standard $\pm 24V$ actuators

Examples with 20A power consumption

- a) 8 pcs. WMX 826-1
- b) 4 sets of 2 pcs. WMX 826-2
- c) 4 pcs. WMU 861-1
- d) 2 sets of 2 pcs. WMU 842-2

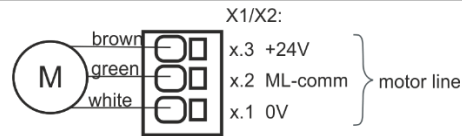
### Connection variant of standard actuators on motor line X1



### MotorLink® actuators

Examples with actuators per motor line

- Ex. 1: 4 pcs. WMX 823-1
- Ex. 2: 2 pcs. WMU 842-2
- Ex. 3: 3 pcs. WMU 826-3

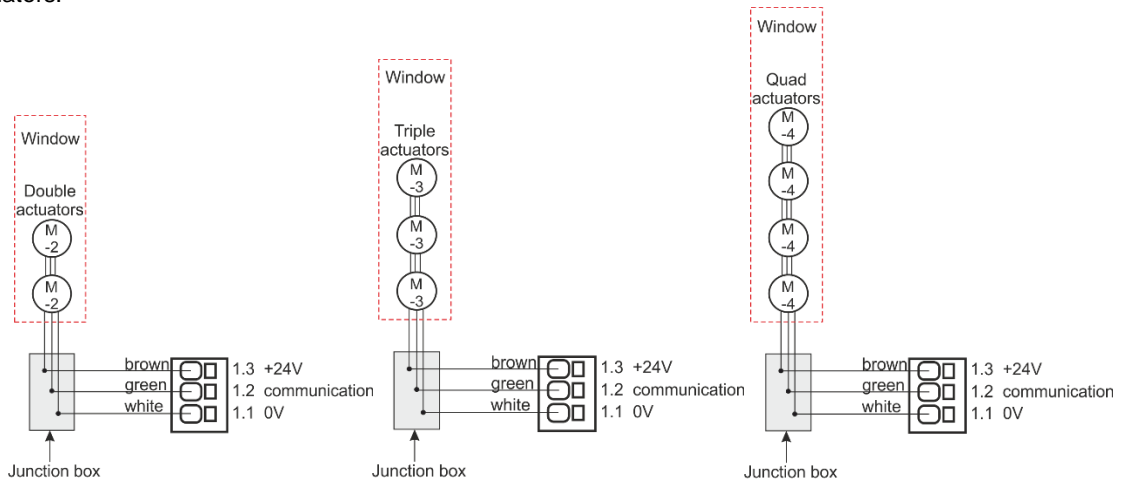
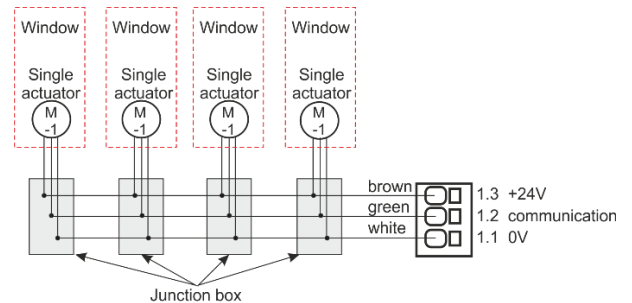


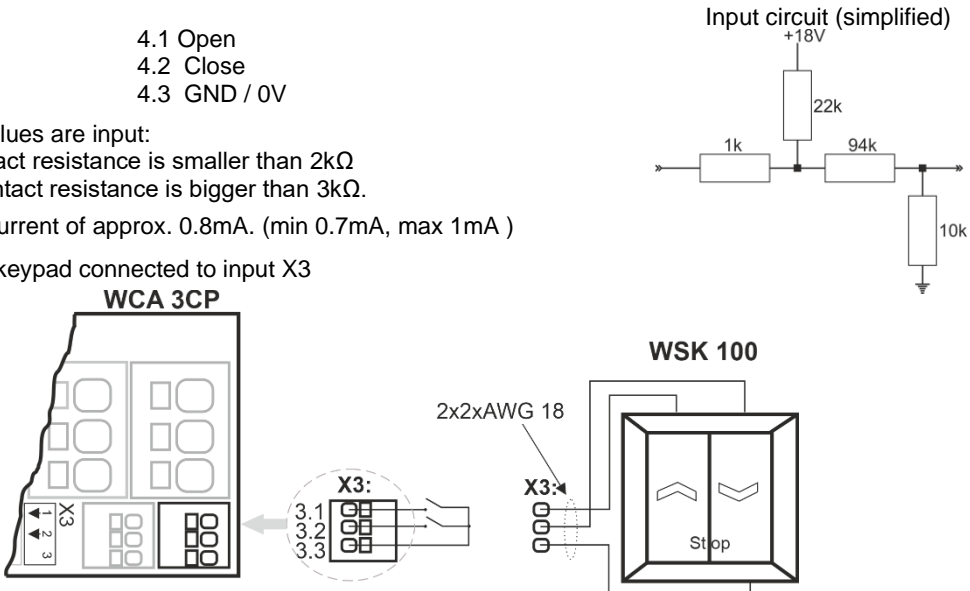
ML-comm = MotorLink™ communication

### Allowed actuator combinations on a MotorLink® motor line

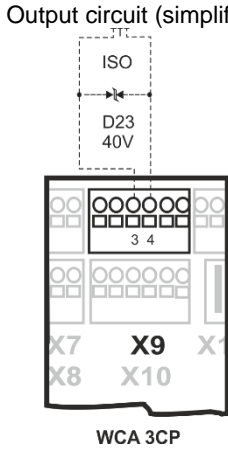
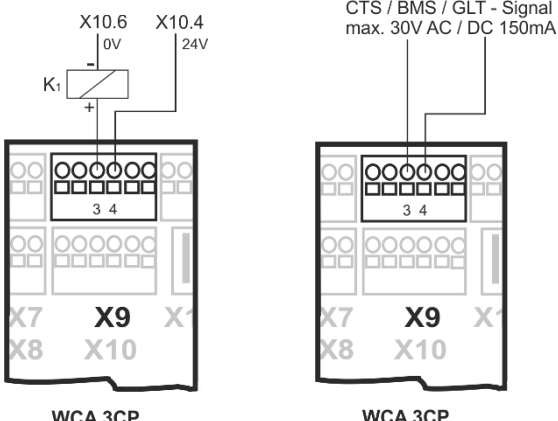
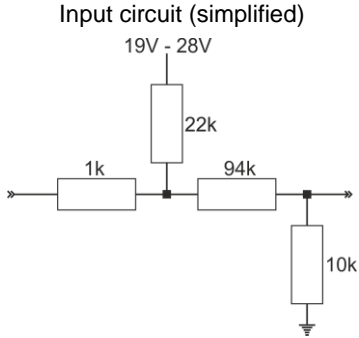
The two motor lines on the CP card can each be connected to one of the below shown combinations.

- 1 (single): one window with one single window actuator. Up to four windows each with one single window actuator can be connected
- 2 (double): one window with two double window actuators.
- 3 (triple): one window with three triple window actuators.
- 4 (quad): one window with four quad window actuators.



<b>S1</b> <b>X3 / X4</b>	<p>For connection of comfort keypads. S1.X3 and S1.X4 are potential free / dry contact.</p> <p><u>Data</u></p> <table border="0"> <tr> <td>3.1 Open</td><td>4.1 Open</td></tr> <tr> <td>3.2 Close</td><td>4.2 Close</td></tr> <tr> <td>3.3 GND / 0V</td><td>4.3 GND / 0V</td></tr> </table> <p>With the default values are input:          "Active" if the contact resistance is smaller than 2k<math>\Omega</math>          "Inactive" if the contact resistance is bigger than 3k<math>\Omega</math>.          Input has pull up current of approx. 0.8mA. (min 0.7mA, max 1mA )</p> <p>Example: comfort keypad connected to input X3</p>  <p>X3 / X4 can also be used as configurable inputs</p> <p><u>Input 1</u></p> <table border="0"> <tr> <td>3.1 input 1.1</td><td></td></tr> <tr> <td>3.2 input 1.2</td><td></td></tr> <tr> <td>3.3 GND 1 / 0V</td><td></td></tr> </table> <p><u>Input 2</u></p> <table border="0"> <tr> <td>4.1 input 2.1</td><td></td></tr> <tr> <td>4.2 input 2.2</td><td></td></tr> <tr> <td>4.3 GND 2 / 0V</td><td></td></tr> </table>	3.1 Open	4.1 Open	3.2 Close	4.2 Close	3.3 GND / 0V	4.3 GND / 0V	3.1 input 1.1		3.2 input 1.2		3.3 GND 1 / 0V		4.1 input 2.1		4.2 input 2.2		4.3 GND 2 / 0V	
3.1 Open	4.1 Open																		
3.2 Close	4.2 Close																		
3.3 GND / 0V	4.3 GND / 0V																		
3.1 input 1.1																			
3.2 input 1.2																			
3.3 GND 1 / 0V																			
4.1 input 2.1																			
4.2 input 2.2																			
4.3 GND 2 / 0V																			
<b>S1</b> <b>X5 / X6</b>	<p>Connection of master / slave connection via WSK-Link™.</p> <p>X5 and X6 are used on the master panel, whereas X11 is used on the slave panel.</p> <p><u>Data</u></p> <table border="0"> <tr> <td>5.1 24V</td><td>6.1 24V</td></tr> <tr> <td>5.2 Communication</td><td>6.2 Communication</td></tr> <tr> <td>5.3 0V</td><td>6.3 0V</td></tr> </table> <p>For connection of WSK-Link™ see X11</p>	5.1 24V	6.1 24V	5.2 Communication	6.2 Communication	5.3 0V	6.3 0V												
5.1 24V	6.1 24V																		
5.2 Communication	6.2 Communication																		
5.3 0V	6.3 0V																		
<b>S1</b> <b>X9</b>	<p>Solid state outputs, one solid state output for transmission of fault signal and 2 free configurable</p> <p><u>Data</u></p> <table border="0"> <tr> <td>9.1 Fault – Open contact = Fault, closed contact = OK</td><td></td></tr> <tr> <td>9.2 Fault – Open contact = Fault, closed contact = OK</td><td></td></tr> <tr> <td>9.3 Output A</td><td></td></tr> <tr> <td>9.4 Output A</td><td></td></tr> <tr> <td>9.5 Output B</td><td></td></tr> <tr> <td>9.6 Output B</td><td></td></tr> </table> <p>Solid state output for transmission of fault signal.          A fault must last at minimum of 20 seconds before the relay indicates a fault.</p> <p><u>Data</u></p> <p>Max voltage: 30 Vp (peak)          Max output: 150 mA          Typical On-resistance: 4.7 <math>\Omega</math>          Max On-resistance: 8 <math>\Omega</math>          Max switching speed: 2 ms</p>	9.1 Fault – Open contact = Fault, closed contact = OK		9.2 Fault – Open contact = Fault, closed contact = OK		9.3 Output A		9.4 Output A		9.5 Output B		9.6 Output B							
9.1 Fault – Open contact = Fault, closed contact = OK																			
9.2 Fault – Open contact = Fault, closed contact = OK																			
9.3 Output A																			
9.4 Output A																			
9.5 Output B																			
9.6 Output B																			



	<p>2 free configurable solid state outputs</p> <p>9.3 Output A 9.4 Output A 9.5 Output B 9.6 Output B</p> <p><u>Data</u> Max voltage: 30 Vp (peak) AC/DC Max current: 150 mA Typical On-resistance: 4.7 <math>\Omega</math> Max On-resistance: 8 <math>\Omega</math> Max switching speed: 2 ms, only for DC-voltage</p>	<p>Output circuit (simplified)</p>  <p>WCA 3CP</p> <p>Example with solid state and relay (polarization is not important)</p>  <p>WCA 3CP      WCA 3CP</p>
<p><b>S1</b> <b>X10</b></p>	<p>For connection of weather station with wind direction.</p> <p>Connection of wind / rain sensors type WLA 330 or WLA 340, rain sensor WLA 331. Or connection of intelligent weather station (wind direction dependent ventilation), e.g. WOW 600 (only with MotorController version U4).</p> <p><u>Data</u> 10.1 24V AUX 10.2 Wind speed 10.3 GND / 0V 10.4 24V (not active in power saving) 10.5 Rain (potential free / dry contact) 10.6 GND / 0V</p> <p>With the default values are input: "Active" if the contact resistance is smaller than 4k<math>\Omega</math> "Inactive" if the contact resistance is bigger than 8k<math>\Omega</math>. For values between 4 and 8k<math>\Omega</math> the result will depend on the supply voltage.</p> <p>Input has pull up current approx. 1mA. (min 0.7mA, max 1.4mA)</p>	<p>Input circuit (simplified)</p> 

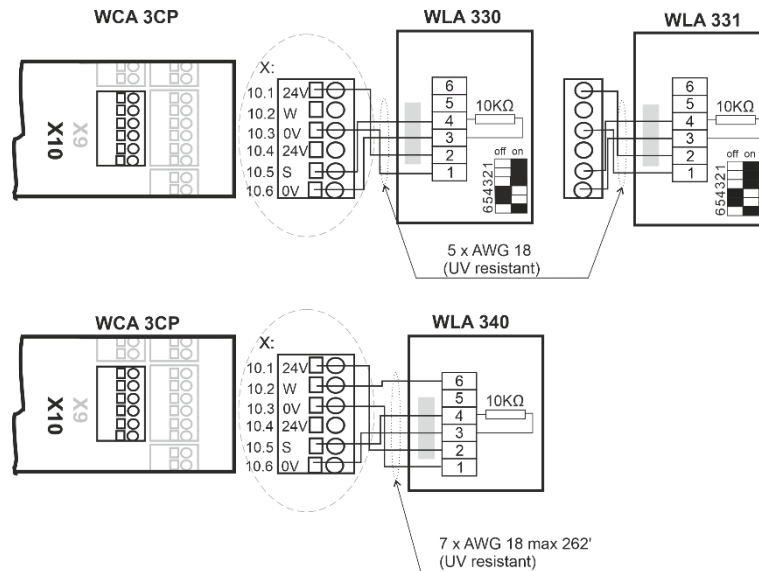
### Example 1: Wind/rain and rain sensors

WLA 330 and WLA 331 – the settings of the sensors are set on the sensor.

WLA 340 – the settings of the sensor are programmable on the MotorControlle's touch screen.

#### Data

- 10.1 24V AUX
- 10.2 Wind speed
- 10.3 GND / 0V
- 10.4 24V
- 10.5 Rain
- 10.6 GND / 0V

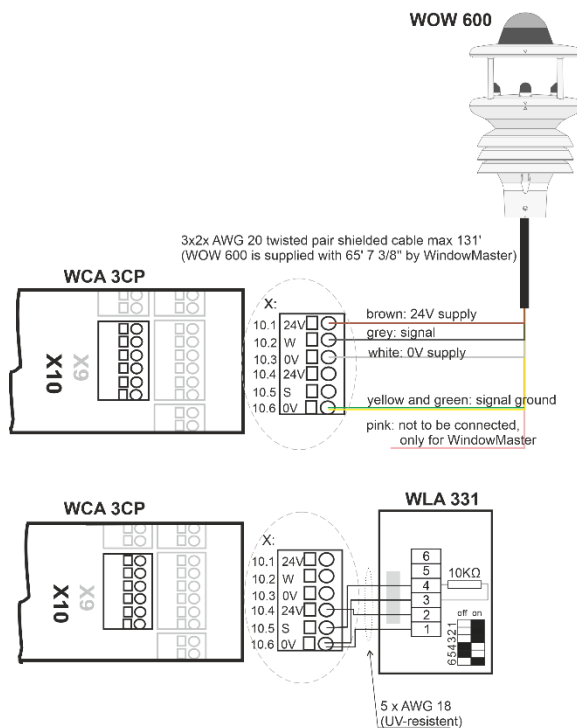


### Example 2: Wind direction dependent ventilation (intelligent weather station)

#### Data

- 10.1 24V AUX
- 10.2 Wind speed / Direction
- 10.3 GND / 0V
- 10.4 24V
- 10.5 Rain
- 10.6 GND / 0V

As the weather station is monitored by both communication and time out (wind without time), any cable errors will be registered. A WOW 600 can only be connected to a MotorController version U4.



## S1 X11

For connection of master / slave connection via WSK-Link™.

### Data:

11.1 24V IN

11.2 Communication IN

11.3 0V IN

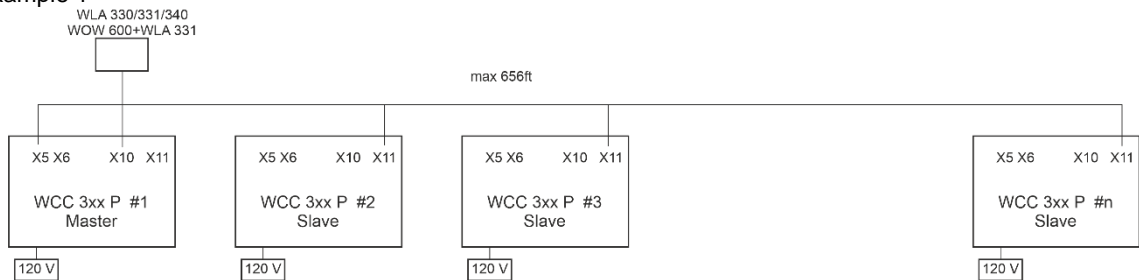
A master-slave connection via WSK-Link™ enables signals to be distributed between several MotorControllers or/and the MotorController may be used as slave in a 120V UPS smoke ventilation system.

On the master MotorController, either use input X5 or X6 for the master-slave connection. On the slave MotorController, the connection is done via X11.

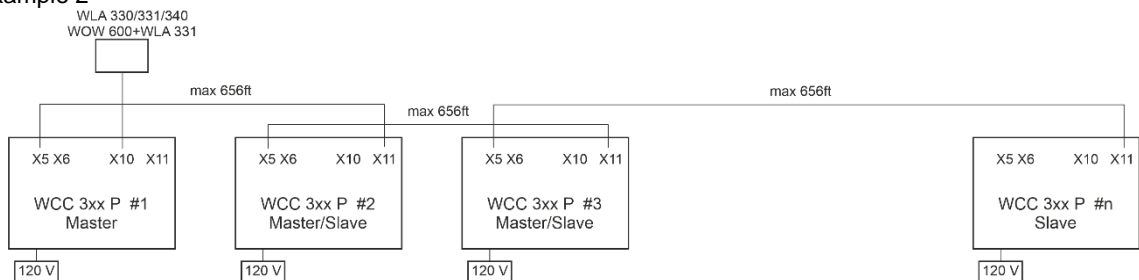
It is possible to connect several MotorControllers in a master slave connection. However, the max total number of MotorControllers on the WSK-Link™ must not exceed 10 units. The max cable length between two units must not exceed 656ft, see examples below, for how to connect the MotorControllers.

### Sharing of signals from weather station

#### Example 1



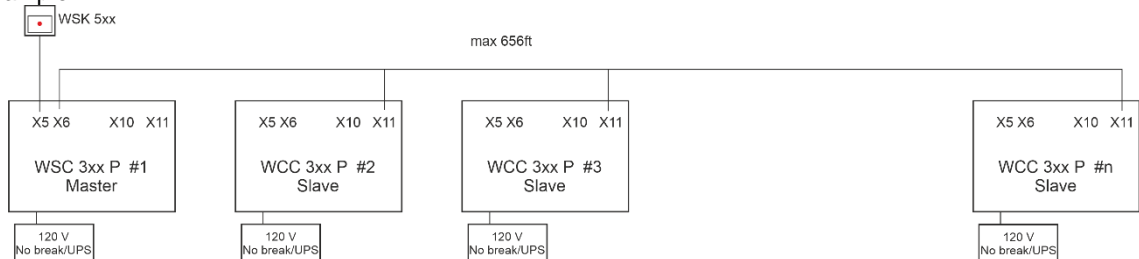
#### Example 2



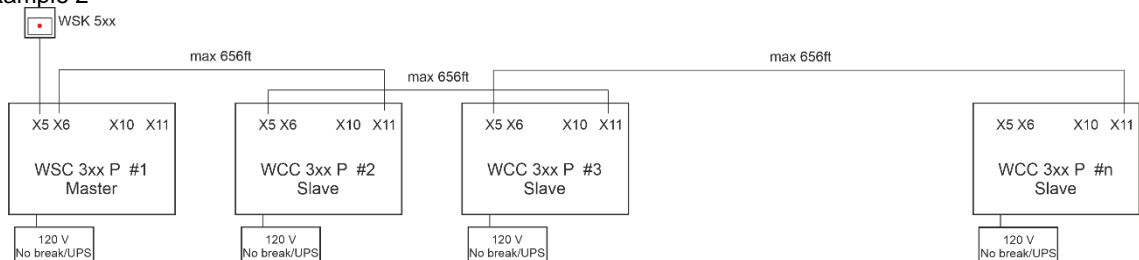
MotorController #2 and #3 are both master and slave MotorControllers.  
See under X10 for connection of weather station

### WCC 3xx as slave in a 120V UPS supplied smoke ventilation system

#### Example 1



#### Example 2



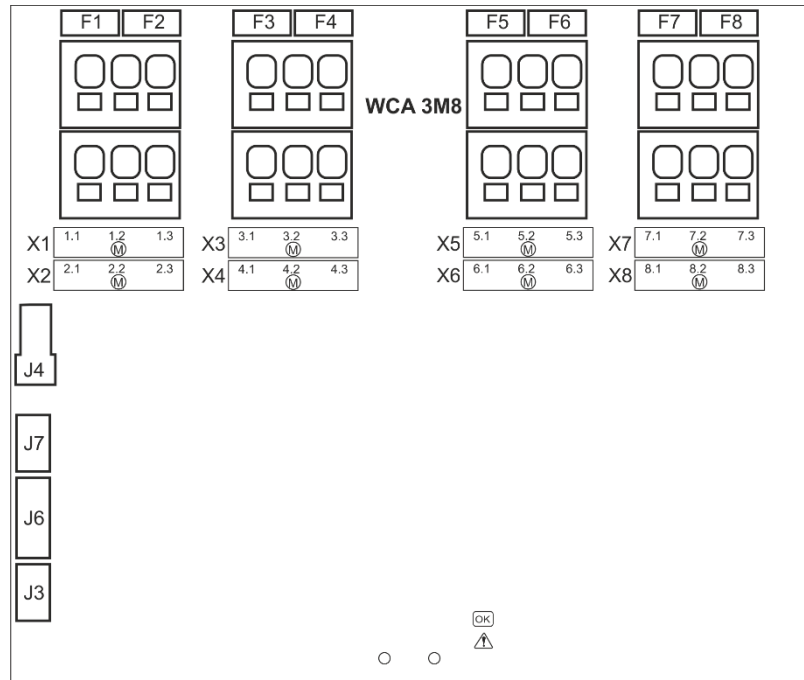
See WSC 3xx instruction for further information about connection to smoke ventilation system.

	Even though the connecting method of MotorControllers shown in the #2 example, enables a physical larger system, with longer distances between MotorControllers, WindowMaster recommends connecting the master slave MotorControllers as shown in example #1. As only the master sends e.g. smoke commands and slaves only respond to commands received from the master, the response time in example 2 is heavily increased in comparison with the response time in example 1.
<b>F2 - F3</b>	3.15A fuse for motorline (WCA 308)
<b>J1</b>	Connection for power supply
<b>J2</b>	Power to motor line card (WCA 3M4 / WCA 3M8)
<b>J3</b>	Connection to AUX (WCA 3P6) – 120V supply
<b>J4</b>	Connection for motor line card (WCA 3M4 / WCA 3M8)
<b>J7</b>	2 x Ethernet connection
<b>J8</b>	USB host. Used to store configurations and to start an event log for e.g. trouble shooting
<b>J9</b>	USB device. Used for remote control and to flash the MotorController.
<b>J10</b>	Connection for fieldbus card
<b>P1</b>	Power supply control
<b>R / P</b>	Reset / programming (used for firmware updates)
<b>LED</b>	Shows the status of the MotorController Yellow = fault, flashing yellow = service timer expired, time for service Green fast flickeing = CPU working, Green constant = CPU communication stopped (possible reset or contact WindowMaster)
↓ ↑	Close / open all windows
<b>BH1</b>	vBAT, back-up battery for CPU and system clock  The VBAT battery is a 3V lithium coin cell battery, which keeps the CPU and system clock running in case of total power failure (both mains and mains backup battery failure). If VBAT voltage drops below 1.65 V an vBAT error can be seen in the power supply menu and the battery must be replaced. vBAT type: 1 pcs. Lithium CR 1220 3V

## 11.4 Motor line card – WCA 3M4 / WCA 3M8

The motor line cards WCA 3M4 and WCA 3M8, allows connection of additional 4 and 8 motor lines respectively either  $\pm 24V$  standard or MotorLink<sup>®</sup>

The WCA 3M4 / WCA 3M8 is connected to WCA 3CP via a CAN-cable (J3 on WCA 3M4 / WCA 3M8 and J4 on the WCA 3CP).



**X1** 1.1 24V / 0V  
1.2 MotorLink  
1.3 0V / 24V } Motorline

**X2** 2.1 24V / 0V  
2.2 MotorLink  
2.3 0V / 24V } Motorline

**X3** 3.1 24V / 0V  
3.2 MotorLink  
3.3 0V / 24V } Motorline

**X4** 4.1 24V / 0V  
4.2 MotorLink  
4.3 0V / 24V } Motorline

**X5** 5.1 24V / 0V  
5.2 MotorLink  
5.3 0V / 24V } Motorline

**X6** 6.1 24V / 0V  
6.2 MotorLink  
6.3 0V / 24V } Motorline

**X7** 7.1 24V / 0V  
7.2 MotorLink  
7.3 0V / 24V } Motorline

**X8** 8.1 24V / 0V  
8.2 MotorLink  
8.3 0V / 24V } Motorline

**F1-F8** Fuse 3.15A

**J3** Connection for main control module

**J4** Power connection from main control module (WCA 3CP)

**J6** Connection to input expansion module (WCA 3KI)

**J7** Power supply control

**S2**  
**X1 - X8**

For connection of  $\pm 24$  Standard actuators or MotorLink<sup>®</sup> actuators.

Data:

x.1 24V / 0V

x.2 ML Communication

x.3 0V / 24V

For actuator connections, please see explanation in section "WCA 3CP main control card" under "X1 / X2" and "Max number of actuators per card".

**F1 - F8**

3.15A fuse for motorline (WCA 308)

**J3**

Connection to main control card (WCA 3CP)

**J4**

Power connection from control card (WCA 3CP)

**J6**

Connection to input card (WCA 3KI)

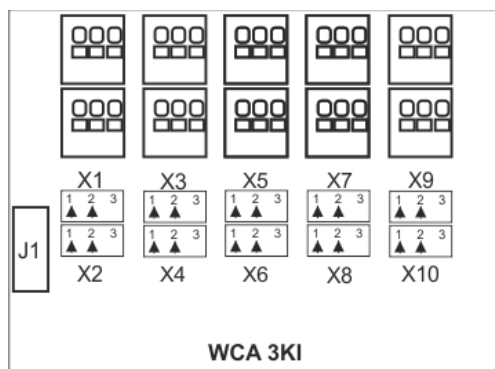
**J7**

Power supply control

## 11.5 Keypad card – WCA 3KI

The keypad card allows connection of 10 keypads. WCA 3KI requires the WCA 3M4 / WCA 3M8 actuator card.

The WCA 3KI is connected to WCA 3M4 / WCA 3M8 via cable (J1 on the WCA 3KI and J6 on the WCA 3M4 / WCA 3M8).



<b>X1</b>	1.1 Open 1.1 1.2 Close 1.2 1.3 GND / 0V	} Comfort keypad #1	<b>X7</b>	7.1 Open 7.1 7.2 Close 7.2 7.3 GND / 0V	} Comfort keypad #7
<b>X2</b>	2.1 Open 2.1 2.2 Close 2.2 2.3 GND / 0V	} Comfort keypad #2	<b>X8</b>	8.1 Open 8.1 8.2 Close 8.2 8.3 GND / 0V	} Comfort keypad #8
<b>X3</b>	3.1 Open 3.1 3.2 Close 3.2 3.3 GND / 0V	} Comfort keypad #3	<b>X9</b>	9.1 Open 9.1 9.2 Close 9.2 9.3 GND / 0V	} Comfort keypad #9
<b>X4</b>	4.1 Open 4.1 4.2 Close 4.2 4.3 GND / 0V	} Comfort keypad #4	<b>X10</b>	10.1 Open 10.1 10.2 Close 10.2 10.3 GND / 0V	} Comfort keypad #10
<b>X5</b>	5.1 Open 5.1 5.2 Close 5.2 5.3 GND / 0V	} Comfort keypad #5			
<b>X6</b>	6.1 Open 6.1 6.2 Close 6.2 6.3 GND / 0V	} Comfort keypad #6	<b>J1</b>	Connection to actuator card (WCA 3M8)	

**S3**  
**X1**  
–  
**X10**

S3.X1 – S3.X10 are potential free / dry contacts.

Data:  
x.1 Open x.1  
x.2 Close x.2  
x.3 GND / 0V

↓↑

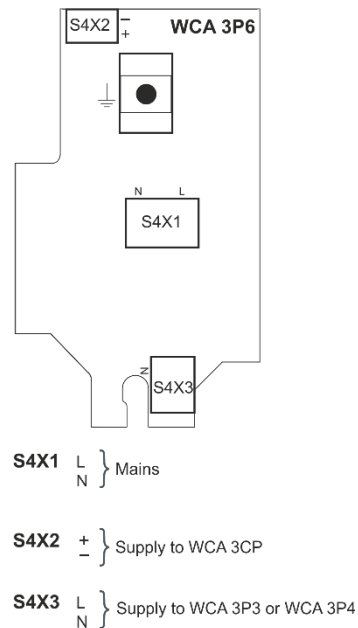
For input connections, please see explanation in section “WCA 3CP main control card” under “X3 / X4”.


**J1**

Connection to motor line card (WCA 3M4 and WCA 3M8)

## 11.6 Power supply card – WCA 3P6

Mains and protective earth is connected to the MotorController via the power supply card.



<b>S4 X1</b>	Connection to mains.
<b>S4 X2</b>	AUX connection to WCA 3CP.
<b>S4 X3</b>	Connection to power supply WCA 3P3 (10A) or WCA 3P4 (20A)
	Protective earth (PE).

## 11.7 Fieldbus cards

Different versions of fieldbus cards are available

- WCA 3FK                      Fieldbus card with KNX interface
- WCA 3FM                    Fieldbus card with BACnet MSTP interface
- WCA 3FB                    Fieldbus card with BACnet IP interface

The connection of a fieldbus card enables communication and access to the available bus-objects depending on the chosen system. There is a set of KNX and BACnet objects available for each motor line and motor group, which provides the options for status and commands.

### Status options

E.g. actual position, fault and operation status and the max opening angle (degrees).

### Command options

E.g. target position commands with different priority and MotorLink® actuator speed. See "WCA 3FK Application Programming Description.pdf" and BACnet PICS for further information on available KNX and BACnet communication objects.

## 12 Touch screen

The plus version of the MotorController comes with a touch screen. All connected components (actuators, keypads, weather station etc.) are to be configured on the touch screen.

The menu of the touch screen is in steps:

Step 1: main menu

Step 2: sub menu

Step 3: configuration / showing / operation of the sub menu

Step 1: **Main menu**

Step 2: **Sub menu**

Step 3: **Configuring** the sub menu

Step 4: **Showing** the sub menu

**Help text**

#### Help text

The touch screen has a help function with text explaining the menu item.

The help text occurs when the menu item is pressed (text on white background).

For displaying the help text:

→ press the item e.g. "Motor type"

→ the help text appears

→ to turn off the help text press the screen.

## 12.1 Icons

The MotorController has icons for quick viewing of: fire conditions, hardware OK and hardware error:



**Hardware OK:** actuators have been configured correctly.



**Hardware error:** hardware error or connected actuators have not been configured correctly in motor lines or motor groups

## 12.2 Rotation of the touch screen

The picture on the touch screen can be rotated 180°



## 13 Configuration – main menu

All connected components (actuators, keypads, weather station etc.) are to be configured.


As the MotorController has pre-settings for PIN code for access to level 3, the code is to be entered before it is possible to begin the configuration (see chapter 12.10 "Log in").


Before starting on the configuration it can be an advantage to change some of the pre-set settings. Ex. the language can be changed from English to Danish or German (see chapter 12.12 "System") and the orientation of the text on the touch screen can be rotated for a better viewing angle (see chapter 12.12 "System"). It is also possible to change the log out time, which is the time that the access to the access level is open/the touch screen in on (see chapter 13.10 "Log in")

To configure a sub menu:

→ press the light blue number field

→ enter value / the number of the motor line / change factory settings etc. The setting which can be entered depends of the type of the sub menu.

→ accept on 

A menu can consist of more screen plays. To get to the next screen: → press 

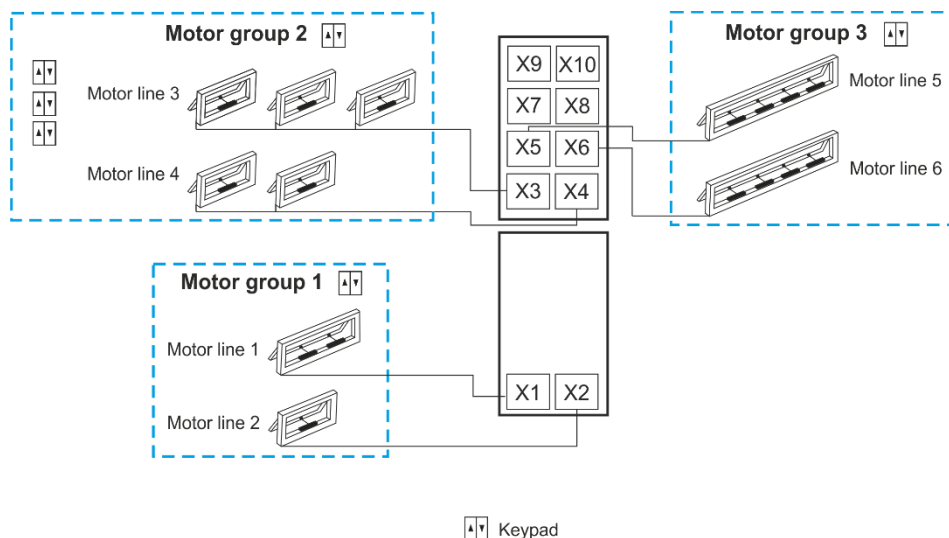
### 13.1 Motor lines – motor groups

All the components are to be assigned to groups:

- motor lines are to be assigned to motor groups
- keypads are to be assigned to one or more motor groups

#### 13.1.1 Examples with motor lines / motor groups

- 6 motor lines: one or more actuators connected to the lines
- 3 motor groups: the actuators in the motor group are operated simultaneously on the keypad

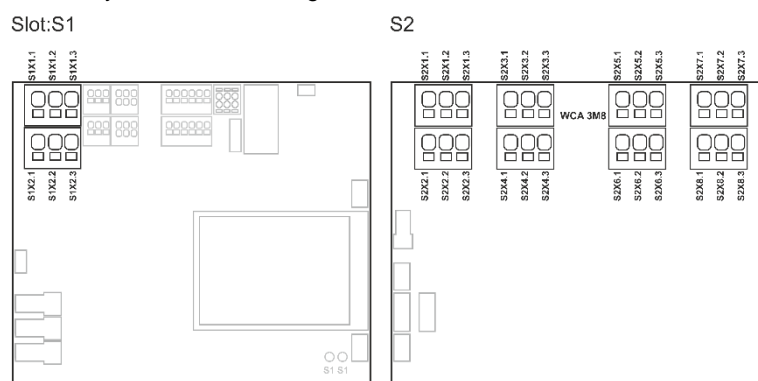


## 13.2 Motor line

Actuators are to be connected on the motor lines.  $\pm 24V$  standard actuators and actuators with MotorLink® can be connected to all motor lines, but a motor line can only be connected to one type of actuators – either  $\pm 24V$  standard or MotorLink® actuators.

### 13.2.1 Motor line - numbering

All motor lines are numbered and they are all to be configured.



### 13.2.2 Motor line - configuration

Press "Motor line" and the overview of the motor lines in the MotorController is shown.

Overview configuration motor lines	
<div style="border: 1px solid black; padding: 10px; margin-bottom: 10px;"> <div style="display: flex; align-items: center;"> <span>Configuration, Motor line</span> </div> <div style="display: flex; justify-content: space-around; margin-top: 5px;"> <div style="border: 1px solid black; padding: 2px 5px;">All</div> <div style="border: 1px solid black; padding: 2px 5px;">X1 </div> <div style="border: 1px solid black; padding: 2px 5px;">X2</div> </div> <div style="margin-top: 20px; text-align: center;"> <div style="border: 1px solid black; padding: 5px; width: 40px; margin: 0 auto;">↻</div> </div> </div> <p style="text-align: center; margin-top: 10px;">One motor line is marked with a  as the configuration is missing.</p>	<div style="border: 1px solid black; padding: 10px; margin-bottom: 10px;"> <div style="display: flex; align-items: center;"> <span>Configuration, Motor line</span> </div> <div style="display: flex; justify-content: space-around; margin-top: 5px;"> <div style="border: 1px solid black; padding: 2px 5px;">All</div> <div style="border: 1px solid black; padding: 2px 5px;">X1</div> <div style="border: 1px solid black; padding: 2px 5px;">X2</div> </div> <div style="margin-top: 20px; text-align: center;"> <div style="border: 1px solid black; padding: 5px; width: 40px; margin: 0 auto;">↻</div> </div> </div> <p style="text-align: center; margin-top: 10px;">All motor lines are configured.</p>





Both actuators outputs on the main control card as well as the four or eight actuators outputs on the motor line card – if such is connected – are to be configured:

- Motor lines with actuators connected are to be configured in "motor group"
- Motor lines with no actuator connected are set to "none"

Since  $\pm 24V$  actuators and actuators with MotorLink® are not to be configured exactly the same way, both type of actuators are listed below with the settings that are to be configured for each actuator type. Be aware that both types of actuators can be connected to the MotorController at the same time.


For  $\pm 24V$  actuators the full chain length is define as a runtime of 60 seconds. When the MotorController is to be 100% sure that the windows ae 100% open or closed, the chain length is run twice (120). This can have an influence when configuring the a sequence control.

Motor lines configuration	
<div style="border: 1px solid black; padding: 10px; margin-bottom: 10px;"> <div style="display: flex; align-items: center;"> <span>Configuration, Motor line, X1</span> </div> <div style="margin-top: 10px;"> <div style="display: flex; justify-content: space-between; margin-bottom: 5px;"> <span>Output mode</span> <div style="border: 1px solid black; padding: 2px 5px;"><math>\pm 24V</math> motor</div> </div> <div style="display: flex; justify-content: space-between; margin-bottom: 5px;"> <span>Motor configuration</span> <div style="border: 1px solid black; padding: 2px 5px;">No cable monitoring</div> </div> <div style="display: flex; justify-content: space-between; margin-bottom: 5px;"> <span>Stroke time</span> <div style="border: 1px solid black; padding: 2px 5px;">60 s</div> </div> <div style="display: flex; justify-content: space-between; margin-bottom: 5px;"> <span>Motor group</span> <div style="border: 1px solid black; padding: 2px 5px;">-</div> </div> <div style="display: flex; justify-content: space-between; margin-top: 10px;"> <div style="border: 1px solid black; padding: 5px; width: 40px; text-align: center;">↻</div> <div style="border: 1px solid black; padding: 5px; width: 40px; text-align: center;">↓</div> </div> </div> <p style="text-align: center; margin-top: 5px;"><math>\pm 24V</math> actuator configuration</p> </div>	<p><b>The <math>\pm 24V</math> actuators can be configured in:</b></p> <ol style="list-style-type: none"> <li>1. Output mode: informs the type of the actuator selected</li> <li>2. Motor configuration</li> <li>3. Stroke time</li> <li>4. Motor group</li> </ol> <p>The appendix contains all the menus that can be configured - see appendix for detailed explanation.</p>
The MotorLink® actuators are to be configured in:	
<div style="border: 1px solid black; padding: 10px; margin-bottom: 10px;"> <div style="display: flex; align-items: center;"> <span>Configuration, Motor line, X1</span> </div> <div style="margin-top: 10px;"> <div style="display: flex; justify-content: space-between; margin-bottom: 5px;"> <span>Output mode</span> <div style="border: 1px solid black; padding: 2px 5px;">MotorLink™</div> </div> <div style="display: flex; justify-content: space-between; margin-bottom: 5px;"> <span>Expected no. of motors</span> <div style="border: 1px solid black; padding: 2px 5px;">1</div> </div> <div style="display: flex; justify-content: space-between; margin-bottom: 5px;"> <span>Motor group</span> <div style="border: 1px solid black; padding: 2px 5px;">-</div> </div> <div style="display: flex; justify-content: space-between; margin-bottom: 5px;"> <span>Expected no. of locking motors</span> <div style="border: 1px solid black; padding: 2px 5px;">None</div> </div> <div style="display: flex; justify-content: space-between; margin-top: 10px;"> <div style="border: 1px solid black; padding: 5px; width: 40px; text-align: center;">↻</div> <div style="border: 1px solid black; padding: 5px; width: 40px; text-align: center;">↓</div> </div> </div> <p style="text-align: center; margin-top: 5px;">MotorLink® motor configuration</p> </div>	<ol style="list-style-type: none"> <li>1. Output mode: informs the type of the actuator selected</li> <li>2. Expected no. of motors (<i>displayed if actuator type = MotorLink®</i>)</li> <li>3. Motor group</li> <li>4. Expected no. of locking motors               <ol style="list-style-type: none"> <li>4.1 No. of found locking motors (<i>see appendix</i>)</li> </ol> </li> </ol> <p>The appendix contains all the menus that can be configured - see appendix for detailed explanation.</p>

Motor lines – synchronisation of ML1 and ML2 configuration	
<div>  View all details, Motor line, S1 X1 </div> <div> Chain length                      263 counts  Service position                30 counts  Position scale                    105  Synchronise with ML 2        Yes </div> <div>    </div> <div>Synchronisation of ML1 &amp; ML2</div>	<p>When motor line ML1 and ML2 are to be synchronised / run as a single motor line "Synchronise with ML2" must be set to "Yes".</p> <p>The configuration is made in the "Motor Line" menu under S1X1 in "View all details".</p> <p>Only the two motor lines on the main card can be synchronised - S1X1 and S1X2. All motors connected to ML1 and ML2 must be of the same type and configuration and be MotorLink™ motors.</p> <p>Synchronisation of motor lines requires FW 2.15.</p>

### 13.2.3 Colour code - motor line

The overview fields on the touchscreen have colour codes for the motor lines:



Colour	Meaning
Yellow triangle icon 	Fault in the configuration or actuator
Strikethrough grey	No configuration of the motor line / the motor line doesn't exist
Black text	The motor line are configured, the actuator has not been closed
Green	The motor line has been configured; the actuator has been closed MotorLink® motor lines will be marked in green, if the actuator / actuators on the motor line has been closed 100% and the point zero of the actuator has been determined.
Light grey number	The motor line are configured with 'No actuator are connected'
Blue ?	Configuration is missing

## 13.3 Motor group

Motorlines can be assigned to motor groups. See the example "Example of motor lines / motor groups" in the beginning of this chapter for further details.


### 13.3.1 Motor group - configuration

Press "Motor group" and the overview of the motor groups in the MotorController is shown.

Motor group configuration													
<div><div></div><div>Configuration, Motor group</div></div> <div><table><tr><td>1</td><td>2</td><td>3</td><td>4</td><td>5</td><td>6</td></tr><tr><td>7</td><td>8</td><td>9</td><td>10</td><td></td><td></td></tr></table></div> <div><div></div></div>	1	2	3	4	5	6	7	8	9	10			<p><b>Motor groups are to be configured in:</b></p> <ol style="list-style-type: none"><li>1. Comfort open position</li><li>2. Comfort open close time</li><li>3. Wind directions where to close during alarm</li></ol> <p>The appendix contains all the items that can be configured - see appendix for detailed explanation.</p>
1	2	3	4	5	6								
7	8	9	10										

### 13.3.2 Colour code – motor group

The overview fields on the touch screen have colour codes for the motor groups:

Colour	Meaning
Yellow triangle icon 	One or more of the assigned motor lines has a failure
Black text	The motor group is configured
Green field	All the assigned motor lines are closed
Light grey number	The motor group is configured but no motor lines are assigned
Blue ?	Configuration is missing

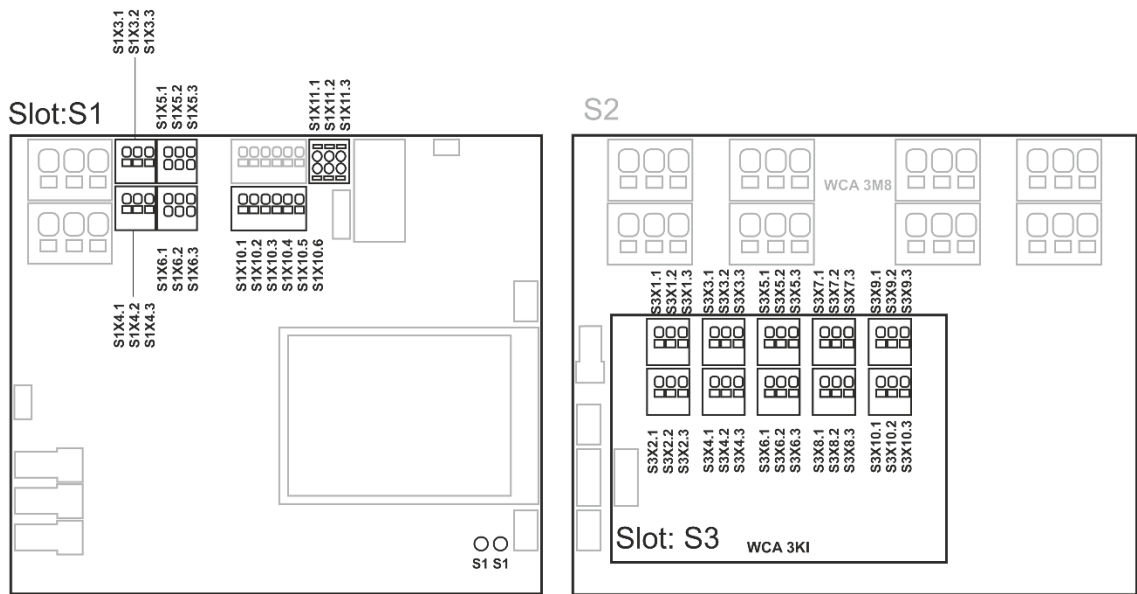
13.4 Local input

The MotorController has two programmable inputs and one input for wind/rain. If further inputs are needed, the input card WCA 8KI (requires the motor line card) can be added. This card has ten local inputs.

The touch screen has an overview of the local inputs.

13.4.1 Numbering of local inputs

All local inputs are numbered.  
The number of the input depends on its location on a card - see overview below.



MotorController with input card

13.4.2 Local input - configuration

If component are installed in one or more inputs, these inputs are to be configured.  
Which item to be configured depends on the type of input – see description below.

## Local input - configuration

Configuration, Local input

-	S1X7.x Smoke	S1X10.5 Safety	S1 X3.1	S1 X3.2	S1 X4.1
S1 X4.2	S1 X8.x	S1 Close	S1 Open	S3 X1.1	S3 X1.2
S3 X2.1	S3 X2.2	S3 X3.1	S3 X3.2	S3 X4.1	S3 X4.2
S3 X5.1	S3 X5.2	S3 X6.1	S3 X6.2	S3 X7.1	S3 X7.2

Overview 'Local input'

Example of overview 'Local input' with connected input card (WCA 3KI)

“S1 Close” and “S1 Open” are the two buttons on the board.

Configuration, Local input, X3.1

Input type                      Binary

Control smoke zones        -

Control motor groups        -

Active state                    On

Configuration of local input X3 and X4

### Input X3 and X4 on WCA 3CP and X1-X10 on WCA 8KI (binary)

If local inputs are connected on the card/cards WCA 3CP and/or WCA 8KI, it/they shall be configured in:

1. Input type: informs the type of the input “Binary) (not to be configured)
2. Control motor groups
  - 2.1 Function in controlled motor groups
  - 2.2 Short output function

The appendix contains all the items that can be configured - see appendix for detailed explanation.

### 13.4.3 Usage of wind/rain sensors - WLA 33x

Usage of wind/rain sensors WLA 33x with motor groups (MG):									
<div style="border: 1px solid black; padding: 5px; margin-bottom: 10px;"> <div style="display: flex; align-items: center;"> <div style="width: 20px; height: 20px; background-color: green; margin-right: 5px;"></div> <div>Configuration, Local input, Safety X10.5</div> </div> <table style="width: 100%; border-collapse: collapse;"> <tr> <td style="width: 60%;">Input type</td> <td style="text-align: center;">Binary</td> </tr> <tr> <td>Control motor groups</td> <td style="text-align: center; border: 1px solid black;">1</td> </tr> <tr> <td>Active function in controlled motor groups</td> <td style="text-align: center; border: 1px solid black;">-</td> </tr> <tr> <td>Inactive function in controlled motor groups</td> <td style="text-align: center; border: 1px solid black;">-</td> </tr> </table> <div style="display: flex; justify-content: space-around; margin-top: 10px;"> <div style="border: 1px solid black; padding: 5px; text-align: center;">↶</div> <div style="border: 1px solid black; padding: 5px; text-align: center;">↓</div> </div> </div>	Input type	Binary	Control motor groups	1	Active function in controlled motor groups	-	Inactive function in controlled motor groups	-	<p>The used input e.g. S1X10.5 is configured to “Control motor groups”, the groups are chosen.  Then, in the menu “Active function in controlled motor groups” the function “Safety” is selected.  Then, a function for the motor group when inactive can be selected “Inactive function in the controlled motor groups”.</p> <p>By each motor group it is possible to define the max opening for “Safety”, meaning it is possible to allow windows and louvers inside the building to open despite “Safety” (wind/rain).</p> <p>Facade windows, which are allowed to open e.g. 10%, to open despite it rains.</p>
Input type	Binary								
Control motor groups	1								
Active function in controlled motor groups	-								
Inactive function in controlled motor groups	-								
Input shall be configured in:									
<div style="border: 1px solid black; padding: 5px; margin-bottom: 10px;"> <div style="display: flex; align-items: center;"> <div style="width: 20px; height: 20px; background-color: green; margin-right: 5px;"></div> <div>Configuration, Local input, S1X10.5 Safety: Active function in controlled</div> </div> <table style="width: 100%; border-collapse: collapse; text-align: center;"> <tr> <td style="width: 50%;">-</td> <td style="width: 50%;">Open</td> </tr> <tr> <td>Close</td> <td>Stop</td> </tr> <tr style="background-color: #90EE90;"> <td>Safety</td> <td>Comfort open</td> </tr> <tr> <td>Comfort step</td> <td>Auto. position</td> </tr> </table> <div style="display: flex; justify-content: space-around; margin-top: 10px;"> <div style="border: 1px solid black; padding: 5px;">✕</div> <div style="border: 1px solid black; padding: 5px;">✓</div> <div style="border: 1px solid black; padding: 5px; text-align: center;">↓</div> </div> </div> <p style="text-align: center; margin-top: 5px;">Configuration of local input</p>	-	Open	Close	Stop	Safety	Comfort open	Comfort step	Auto. position	<ol style="list-style-type: none"> <li>1. In the motor groups configure the input with the function “Safety”.</li> <li>2. Configure the motor groups when anything else than close (0%) is desired.</li> </ol> <p>Note: motor groups also receive “Safety” signals from the smoke zones they are associated with, see below for further information.</p>
-	Open								
Close	Stop								
Safety	Comfort open								
Comfort step	Auto. position								

## 13.5 Local output

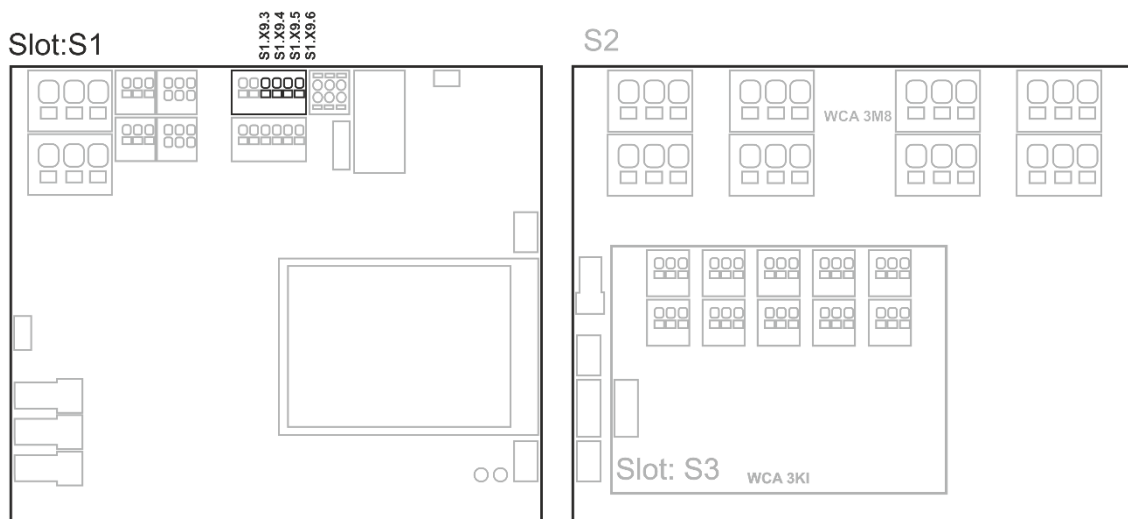
On the WCA 3CP card the MotorController always has one output (X9.1 / X9.2) for fault signal (not configurable output).

### 13.5.1 Numbering of local output

All local outputs on the WCA 3CP card are numbered.

The number of the output depends on its location on the card - see overview below.

As the output (fault signal) on the WCA 3CP card cannot be configured it is not numbered.



MotorController with motor line and input cards

### 13.5.2 Local output - configuration

If component are installed in one or more outputs, these outputs are to be configured.  
Which item to be configured depends on the type of output – see description below.

Local output - overview	
<div><div><div>✓ Configuration, Local output</div><div><div>A</div><div>B</div></div><div><div>X9.3/4</div><div>X9.5/6</div></div></div><div><div>➤</div></div><div>Overview 'Local output'</div></div>	Overview 'Local output'
Local output shall be configured in:	
<div><div><div>✓ Configuration, Local output, A X9.3/4</div><div><div>Output type</div><div>Binary output</div></div><div><div>Output mode</div><div>Binary output</div></div><div><div>Controlled by motor groups</div><div>-</div></div></div><div><div>➤</div></div><div>Configuration of a local output (shown for S1 X9.3/4)</div></div>	<ol style="list-style-type: none"><li>1. Output type: informs the type 'Binary output' (is <i>not</i> to be configured)</li><li>2. Output mode</li><li>3. Controlled by motor groups<ol style="list-style-type: none"><li>a) Motor group output function</li><li>b) Logic function</li><li>c) Status when active</li><li>d) Time-out</li></ol></li></ol> <p>The appendix contains all the items that can be configured - see appendix for detailed explanation.</p>

### 13.6 Weather station type

Here is to be selected which type of weather station –none, WOW or WLA - that is connected.

(The menu "Weather" is only used for input from WCA 3CP input S1X10.2 for wind speed from WLA 340. Input S1X10.2 is also used in combination with weather station WOW 201/202/204 or WOW 600 for wind direction dependent smoke ventilation - see chapter 11.3).

WLA 33x is not considered as a weather station and is connected directly to the input X10.5, see chapter 12.4.3.

Weather - configuration	
<div><div><div>✓ Configuration, Weather</div><div><div>Sensor type</div><div>None</div></div><div><div>WSK Link™ Master present</div><div>Master not present</div></div></div><div><div>➤</div></div><div>Overview 'Sensor type'</div></div>	Overview 'Sensor type' (selection of type of weather station)

### Weather shall be configured in:

☒ Configuration, Weather: Sensor type

None <input checked="" type="checkbox"/>	WOW	WLA 340	From WSK Link™
GMX600	WOW from AOnet	WLA 340 from AOnet	GMX600 from AOnet
WOW from foreign	WLA 340 from	GMX600 from	

☐ ☒

Configuration of the sensor

#### None

(no configuration)

#### WOW

1. Filter constant
2. Slow filter constant
3. Use RMS in filter

#### WLA

1. Pulses/sec. per m/s
2. Filter constant
3. Slow filter constant
4. Use RMS in filter

#### From WSK Link™

(no configuration)

#### WMX600 (only MotorController version U4)

1. Filter constant
2. Slow filter constant
3. Use RMS in filter

#### X from AOnet or foreign (only MotorController version U2, U3 or U4)

AOnet eller foreign is only used in connection with NV Embedded®, please refer to the NV Embedded® instruction for further details.

The appendix contains all the items that can be configured - see appendix for detailed explanation.

## 13.7 Sequence control

The sequence control functionality is used where the movement of a motor line must depend on an external event or situation/stage.

To be used where window flaps are overlapping or where the windows cannot open (more than 15%) if the blinds are down a.s.o.

The sequence control can be controlled depending on;

- the position of a different motor line
- the state of a local input
- the state of a KNX object
- the state of a BACnet object

### Sequence control configuration

☒ Configuration, Motor line, X1

Sequential control type

☐ ☒

Activation of sequence control

The activation of sequence control is to be done for each motor line.

☒ Configuration, Motor line, X1: Sequential control type

None	Open <input checked="" type="checkbox"/>
Close	

☐ ☒

Sequence control configuration

The function for the sequence control is to be configured for each motor line

1. **None** - This motor line does not use sequence control
2. **Open** - This motor line must wait for a "result" before opening
3. **Close** - This motor line must wait for a "result" before closing

Sequence control configuration – motor line	
<div> <div> <input checked="" type="checkbox"/> Configuration, Motor line, X1 </div> <div> <div>Sequential control position limit</div> <div>Closed 0%</div> </div> <div> <div>Sequential control with</div> <div>Motor line</div> </div> <div> <div>Sequential control with no</div> <div>X1</div> </div> <div> <div>Sequential control position logic</div> <div>Greater than or equal</div> </div> <div> <div>↶</div> <div>↑</div> <div>↓</div> </div> </div>	<ol style="list-style-type: none"> <li><b>Sequential control position limit</b> the max position the motor line is allowed to have without the „result“ is being fulfilled. For MotorLink® motor lines stepless variable. For ±24 Volt motor lines 0 or 100%</li> <li><b>Sequential control with</b> (<i>upon what should the motor line wait?</i>) <ol style="list-style-type: none"> <li>Motor line.</li> <li>Local input</li> <li>The state of a KNX object</li> <li>The state of a BACnet object</li> </ol> </li> <li><b>Sequential control with No</b> Upon which number should the motor line wait</li> <li><b>Sequential control position logic</b> In which positions should the sequential control be active</li> </ol>

### 13.8 WSK-Link™ - master/slave connection

The WSK-Link™ connection between to MotorControllers is done via input X5 or X6 on the master and input X11 on the slave. A MotorController can have a master/slave connection to several MotorControllers. However, the total max number of connected slaves on the bus must not exceed 10 units.

The total cable length must not exceed 656ft, see S1 X11 for examples for connection of MotorControllers.

A slave can only have one master, whereas a master can have several slaves and a MotorController can both be a slave and a master to MotorControllers.

Configuration of Master – Slave system:	
<div> <div> <input checked="" type="checkbox"/> Configuration, WSK-Link™ </div> <div> <div>All</div> <div>1</div> <div>2 ?</div> <div>3 ?</div> </div> <div> <div>↶</div> </div> </div> <p>A connected slave MotorController is shown on the master MotorController's touch screen.</p>	<p>When two MotorControllers are connected to each other in a master-slave connection, the slave will appear as a green break glass unit on the master's touch screen.</p>
<div> <div> <input checked="" type="checkbox"/> Configuration, WSK-Link™, no. 1 </div> <div> <div>Device type</div> <div>WCC 3XX</div> </div> <div> <div>Serial number</div> <div>4105404673</div> </div> <div> <div>Associated smoke zone</div> <div>- ?</div> </div> <div> <div>Use comfort inputs in smoke zone</div> <div>Yes</div> </div> <div> <div>↶</div> <div>↓</div> </div> </div> <p>The slave MotorController's appearance on the master MotorController</p>	<p>On the master's touch screen the Device type of the slave will appear as a WCC 3xx.</p>

### 13.9 Network

For configuring network addresses.

The WCA 3CP card has a 10/100Mbit Ethernet connection. The connection support DHCP or static IP address as well as Gateway

The appendix contains all the items that can be configured - see appendix for detailed explanation.

Network is used in with BACnet IP interface – contact WindowMaster for further information.



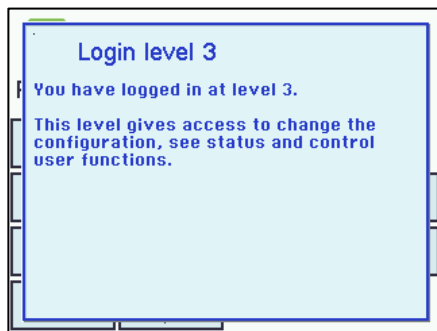
Network shall be configured in:	
<div> <input checked="" type="checkbox"/> Configuration, Network         </div> <div>           DHCP <input type="button" value="Yes"/> </div> <div>           Power setting <input type="button" value="Auto."/> </div> <div> <input type="button" value="↩"/> </div> <div>Configuration of 'Network'</div>	1. DHCP 2. Power setting  The appendix contains all the items that can be configured - see appendix for detailed explanation.

## 13.10 Log in

The access level to the MotorController is set in four levels.

Level	Access to	Who has access
1	<u>Public</u> You can see the MotorController from the outside with the door closed and locked	Everyone
2	<u>Operation</u> You can open the MotorController and operate the touch screen for showing the status and manual operating of the windows.  All the menus on the touch screen can be viewed but no values can be changed.	Chosen persons with a special key
3	<u>Configuration</u> You can open the MotorController and operate the touch screen for showing status, manual operating of the windows as well as configuration and changing the pre-set values.  All the menus and sub menus can be seen and the values can be changed.  Access Level 3 can be locked with a PIN code, so there is only access to the level when the PIN is entered	Chosen persons with a special key and having the PIN code for access to level 3.  PIN code pre-set to 4321.

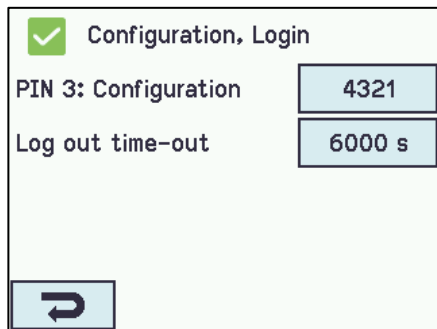
<div> <input checked="" type="checkbox"/> Login level 2         </div> <div>           You are logged out. On the touch screen this means, that you are at login level 2.             This level gives access to see status and control user functions such as opening or closing windows.             To change configuration settings, please log in.         </div> <div>The user is on access level 2</div>	The user is at access level 2.  To open for access level 3, enter the PIN for access level 3.																
<div> <input checked="" type="checkbox"/> Please enter PIN         </div> <div>           PIN code           <table border="1"> <tr> <td>1</td><td>2</td><td>3</td><td></td></tr> <tr> <td>4</td><td>5</td><td>6</td><td>&lt;=</td></tr> <tr> <td>7</td><td>8</td><td>9</td><td>0</td></tr> <tr> <td>✕</td><td>✓</td><td></td><td></td></tr> </table> </div> <div>Enter PIN code</div>	1	2	3		4	5	6	<=	7	8	9	0	✕	✓			Enter PIN code.
1	2	3															
4	5	6	<=														
7	8	9	0														
✕	✓																



Access approved to login level 3

The user is at access level 3.



#### Login shall be configured in:



Configuration of login

The access levels can be locked and access to the level is only possible with a PIN code.  
Each level has a unique PIN code.  
1. PIN 3: Configuration  
2. Log out time-out (the period of access to the level before the system automatically lock the level)

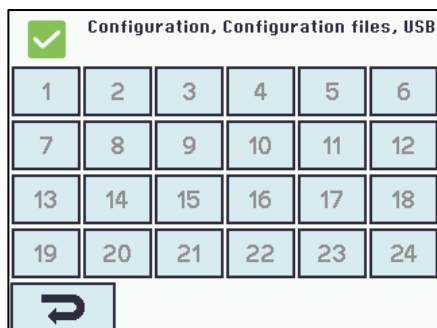
The appendix contains all the items that can be configured - see appendix for detailed explanation.

It is possible to lock the touch screen before the time has expired: press  followed by pressing 

## 13.11 Configuration files on USB

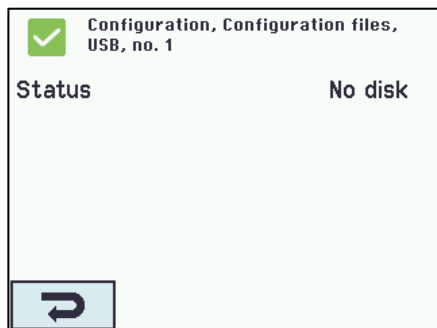
The MotorController has a plug in for an USB stick. It is possible to save all the configurations of the MotorController and this way save the stick as documentation. It is also possible to reinstall from the USB stick.

Files on the USB stick can be printed from a computer.



Configuration 'Configuration, files on USB' - overview

Configuration files on USB – overview.



Configuration of 'Configuration files on USB - no.1'.

Configuration of configuration files on USB – shown for no. 1.

## 13.12 System

It is possible to change settings on the touch screen e.g. language, clock setting, date display, service timer etc.

System can be configured in:	
<div style="border: 1px solid black; padding: 5px;"> <div style="display: flex; align-items: center;"> <div style="width: 20px; height: 20px; background-color: green; margin-right: 5px;"></div> <div>Configuration, System</div> </div> <div style="margin-top: 5px;"> <div style="display: flex; justify-content: space-between;"> <div>Language</div> <div style="border: 1px solid black; padding: 2px 10px;">English</div> </div> <div style="display: flex; justify-content: space-between; margin-top: 5px;"> <div>Backup time stamp</div> <div>-</div> </div> <div style="display: flex; justify-content: space-between; margin-top: 5px;"> <div>Unsaved changes</div> <div>Yes</div> </div> <div style="display: flex; justify-content: space-between; margin-top: 5px;"> <div>Configuration command</div> <div style="border: 1px solid black; padding: 2px 10px;">No command</div> </div> <div style="display: flex; justify-content: space-between; margin-top: 10px;"> <div style="border: 1px solid black; padding: 5px; width: 40px; text-align: center;">↶</div> <div style="border: 1px solid black; padding: 5px; width: 40px; text-align: center;">↓</div> </div> </div> </div>	<ol style="list-style-type: none"> <li>1. Language</li> <li>2. Backup time stamp <i>(not to be configured)</i></li> <li>3. Unsaved changes... <i>(not to be configured)</i></li> <li>4. Configuration command</li> <li>5. Time</li> <li>6. Date</li> <li>7. LCD rotate view</li> <li>8. Enable parameter set from network</li> <li>9. Enable remote control</li> </ol> <p>The appendix contains all the items that can be configured - see appendix for detailed explanation.</p>

Configuration of 'System'

## 13.13 Fieldbus (KNX and BACnet)

Only when an Fieldbus card with a fieldbus interface is added to the MotorController will the menus associated with the various fieldbus options be shown.

Fieldbus example	
<div style="border: 1px solid black; padding: 5px;"> <div style="display: flex; align-items: center;"> <div style="width: 20px; height: 20px; background-color: green; margin-right: 5px;"></div> <div>Configuration</div> </div> <div style="margin-top: 5px;"> <div style="border: 1px solid black; padding: 2px 10px;">Network</div> <div style="border: 1px solid black; padding: 2px 10px; margin-top: 2px;">KNX bus</div> <div style="border: 1px solid black; padding: 2px 10px; margin-top: 2px;">BACnet</div> <div style="border: 1px solid black; padding: 2px 10px; margin-top: 2px;">Login</div> </div> <div style="display: flex; justify-content: space-between; margin-top: 10px;"> <div style="border: 1px solid black; padding: 5px; width: 40px; text-align: center;">↶</div> <div style="border: 1px solid black; padding: 5px; width: 40px; text-align: center;">↑</div> <div style="border: 1px solid black; padding: 5px; width: 40px; text-align: center;">↓</div> </div> </div>	<p>An optional card with fieldbus interface is added to the MotorController and the menus (e.g. configuration) now includes KNX and BACnet.</p>

When the Fieldbus card is mounted a set of KNX or BACnet objects are available for each motor line and motor group, which provides the options for status and commands.

### Status objects

E.g. actual position, fault and operation status and the max opening angle (degrees).

### Command objects

E.g. target position commands with different priority and MotorLink® motor speed.

### Fieldbus link - "Conn. 1-10 "

The KNX or BACnet has also 10 configurable binary communication objects.

These can either be used for sending comfort commands to one or more motor groups or to give selected status from smoke zones or motor groups.

See "KNX Application Program Description or "BACnet PICS" on the home pages ([www.windowmaster.com](http://www.windowmaster.com)) for further information on available KNX or BACnet communication objects.

## 13.13.1 KNX configuration

KNX bus overview – object configuration													
<div style="border: 1px solid black; padding: 5px;"> <div style="display: flex; align-items: center;"> <div style="width: 20px; height: 20px; background-color: green; margin-right: 5px;"></div> <div>Configuration, KNX bus</div> </div> <div style="margin-top: 5px;"> <table border="1" style="width: 100%; text-align: center; border-collapse: collapse;"> <tr> <td style="width: 15%;">Module</td> <td style="width: 15%;">Obj. 1</td> <td style="width: 15%;">Obj. 2</td> <td style="width: 15%;">Obj. 3</td> <td style="width: 15%;">Obj. 4</td> <td style="width: 15%;">Obj. 5</td> </tr> <tr> <td></td> <td>Obj. 6</td> <td>Obj. 7</td> <td>Obj. 8</td> <td>Obj. 9</td> <td>Obj. 10</td> </tr> </table> </div> <div style="display: flex; justify-content: space-between; margin-top: 10px;"> <div style="border: 1px solid black; padding: 5px; width: 40px; text-align: center;">↶</div> </div> </div>	Module	Obj. 1	Obj. 2	Obj. 3	Obj. 4	Obj. 5		Obj. 6	Obj. 7	Obj. 8	Obj. 9	Obj. 10	<p>Overview of the KNX objects.</p> <p>For each KNX object a direction must be configured</p> <ul style="list-style-type: none"> <li>- None</li> <li>- Input</li> <li>- Output</li> </ul> <p>When objects are configured as inputs or outputs, the controlled motor group or smoke zone as well as its function must also be configured.</p>
Module	Obj. 1	Obj. 2	Obj. 3	Obj. 4	Obj. 5								
	Obj. 6	Obj. 7	Obj. 8	Obj. 9	Obj. 10								

**Configuration, KNX bus**

Module type	Konnex
ETS application version	3.00
Physical address	1.1.1
Power setting	Auto.

For all the objects the Power setting for the KNX bus must be configured.

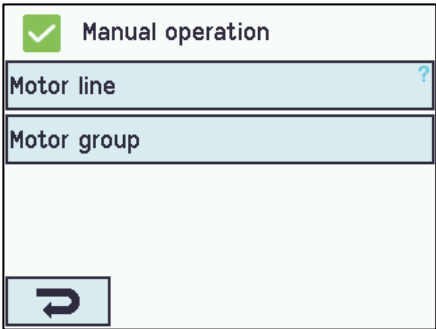
BACnet overview – object configuration	
<div> <div>  Configuration, BACnet </div> <div> <div>Com-mon</div> <div>Obj. 1</div> <div>Obj. 2</div> <div>Obj. 3</div> <div>Obj. 4</div> <div>Obj. 5</div> <div>Obj. 6</div> <div>Obj. 7</div> <div>Obj. 8</div> <div>Obj. 9</div> <div>Obj. 10</div> </div> <div> </div> </div>	<p>Overview of the BACnet objects.</p> <p>For each BACnet object a direction must be configured</p> <ul style="list-style-type: none"> <li>- None</li> <li>- Input</li> <li>- Output</li> </ul> <p>When objects are configured as inputs or outputs, the controlled motor group or smoke zone as well as its function must also be configured.</p>
BACnet shall be configured in:	
<div> <div>  Configuration, BACnet </div> <div> <div>BACnet IP UDP port number</div> <div>47808</div> <div>BACnet IP device instance</div> <div>1</div> <div>Actual position COV increment</div> <div>1%</div> <div>Actual max. position COV increment</div> <div>1%</div> <div> </div> <div> </div> </div> </div>	<p>For all the objects</p> <ol style="list-style-type: none"> <li>1. BACnet IP UDP port number</li> <li>2. BACnet IP device instance</li> <li>3. Actual position COV increment</li> <li>4. Actual max. position COV increment</li> <li>5. High speed COV increment</li> <li>6. Wind direction COV increment</li> <li>7. Register as “foreign device”</li> </ol>

In 'Status' you can see the status of all the menu items that can be configured under 'Configuration' as well as e.g. the status of the power supply and slots (inform the type of card in the slot).

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## 15 Manual operation and main menu

It is possible to operate the motor lines, the motor groups and the smoke zones direct on the touch screen.

	<b>What to be manually operated:</b> <ol style="list-style-type: none"><li>1. Motor line – see text below</li><li>2. Motor group</li></ol>
---	--

Main overview: manual operation

### Operation types

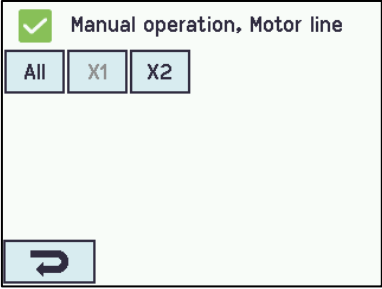
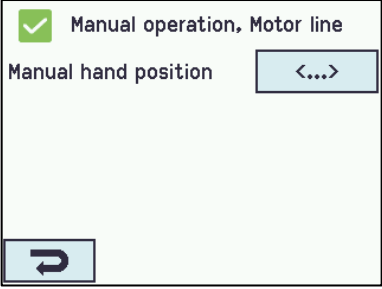
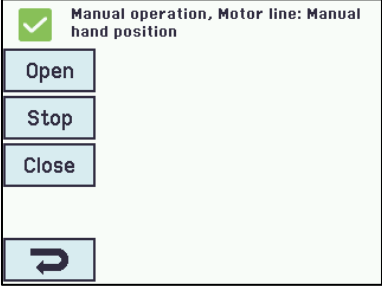
#### Motor lines and motor groups

They can be operated **absolutely** (percentage of full open) or **relatively** on the keypad 'open/stop/close' showed on the touch screen.

Example

#### Manual operation of a motor line

- If 'All' is selected all the actuators are operated simultaneously.
- If a motor line number is selected only the selected motor line is operated.

		
Motor line – overview	One motor line is selected	Manual operation on the touch screen

## 16 Configuration missing – main menu

If any components, motor lines or motor groups are not configured they are listed here. If you are logged into access level 3 it is also possible to configure from this menu.

## 17 Hardware error – main menu

If there are any hardware error on the MotorController, they will be displayed here. E.g. if the motor lines are not configured, the main supply is cut of, the type of weather station is not selected etc. If you are logged into access level 3 it is also possible to configure from this menu.

## 18 View all details – main menu

To make the configuration of the MotorController as simple as possible during configuration, it is only possible to configure the most used functions. Under 'View all details' is displayed all of the above functions together with detailed functions that are not used as often, but are possible to configure. If you are logged into access level 3 it is also possible to configure from this menu.

### It is possible to view all details for:

Motor line  
Motor group  
WSK-Link™  
Local input  
Local output  
Weather  
Power supply  
Network  
KNX-bus  
BACnet  
Slots  
Log in  
Configuration files, USB  
System

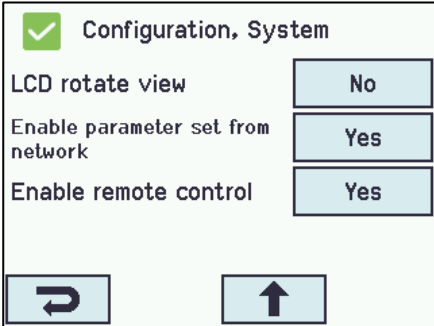
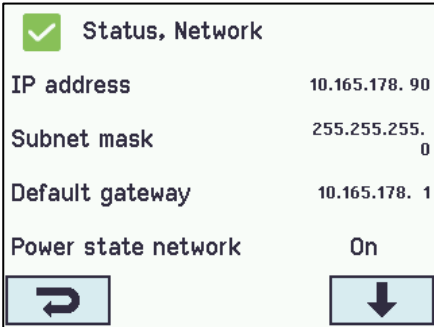
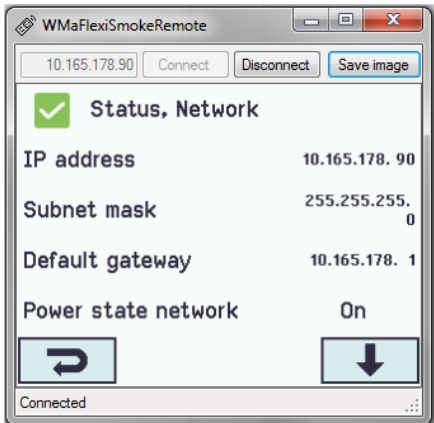
## 19 Remote control of MotorController

It is possible to remote control a MotorController from a PC or via USB device.

When the MotorController is on a standard computer network (Ethernet) you can from any PC with the "WMaFlexiSmokeRemote" program control the MotorController just like if you were standing in front of the itl.

If the MotorController is not connected to a network then it can be remote controlled via a USB connection using the "WMaFlexiSmokeRemote" program.

The program "WMaFlexiSmokeRemote" can be downloaded from our webpages ([www.windowmaster.com](http://www.windowmaster.com)) under WCC 310 or WCC 320.

Remote control can be configured in:	
 <p>Configuration of remote control</p>	<p>To enable remote control of the MotorController it is necessary to allow remote control. This is done in the configuration of the system.</p>
 <p>Identification of the IP-address</p>	<p>IP-address of the MotorController</p>
 <p>Screen shot from the PC when controlling the FlexiSmoke™ remotely</p>	<p>Start the 'WMaFlexiSmokeRemote program' on the connected PC. Enter the IP-address and press 'Connect'.</p>

## 20 Commissioning and test run

In case of hardware error, please see chapter 17 "Hardware error"

We recommend that the software of the MotorController is updated during the annual maintenance check!

### 20.1 The MotorController is completely installed, without the operating voltage applied

- Check all mechanical and electrical components for damage.
- Check all screw and plug connections for tightness and/or firm seating
- Check that all external components are installed:
  - 1)  $\pm 24V$  actuators: Is the motor end module inserted in the last or only actuator?

## 20.2 With mains voltage

Adhere to the relevant regulations!

Connect the mains cables and reapply the mains voltage.

## 20.3 Ventilation keypad

Closely observe the actuators during opening and closing. They must not be impaired in any position by the building structure.

Observe that the actuator cables are not being subject to pulling or pinching.

Check each ventilation keypad individually.

## 20.4 Wind/rain detector

- a) Open the actuators with the comfort ventilation keypads.
- b) Wet the rain sensor, the actuators will fully close.
- c) While the actuators are running, press the Open button at the keypad. The actuators must neither open nor stop!  
Exception: If set to a manual override time (Man. operation after auto comm.).

If the start-up was successful, mount the doors of the MotorController and make back-up.

If the start-up was unsuccessful (error with one of the test run processes), please see chapter 10 "Description of cards".

If necessary, check the wiring in accordance with the cable plan – see chapter 9 "Cable plan for connection to WCC 3xx".

# 21 Maintenance

Control and maintenance should only be done by the manufacturer or an authorized partner. If the MotorController is a part of a smoke ventilation system control and maintenance must be documented by a mark on the MotorController and in the service book.

Remove all soiling from the MotorController. Check fastening and clamping screws for firm seating.

Carry out a test run of the entire system (see chapter 19 'Commissioning and test run').

Only have defective units repaired in our factory. Only install original spare parts.

We recommend that the software of the MotorController is updated during the annual maintenance check!

The expected minimum lifetime for the MotorController is 10 years.

## 21.1 Replacement cards

### 21.1.1 Replacement of 3M4, 3M8 and 3KI cards

1. Disconnect the 120V.
2. Wait until the display has completely turned off before removing the card.
3. Insert the replacement card.
4. Turn on the 120V.
5. The system will be ready again after approx. 2 seconds.

### 21.1.2 Replacement of 3CP card

1. Save a backup of the configuration on a USB stick (recommended).
2. Disconnect the 120V.
3. Wait until the display has completely turned off before removing the card.
4. Insert the 3PS replacement card.
5. Insert the USB stick into the new card.
6. Turn on the 120V.
7. Load the parameters from the USB stick
8. The system will be ready again after approx. 2 seconds.

If the WCA 3CP card, which is to be replaced, is completely without function then go straight to point 2.

If there is no backup of the configurations, these are to be entered manually.

It is therefore recommended to take a backup, on a USB stick, when the MotorController is running, if necessary please see chapter 13.11.

## 21.2 Voltage drop on the vBAT and replacement

<div> <input checked="" type="checkbox"/> View all details, Power supply         </div> <div>           Disable low standby power mode <span>No</span> </div> <div>           Mains off error time <span>28 min.</span> </div> <div>           Standby 5V <span>5.0 V</span> </div> <div>           Vbat <span>3.2 V</span> </div> <div> <span>↶</span> <span>⬆</span> <span>⬇</span> </div>	<p>If VBAT voltage drops below 1,65 V an vBAT error can be seen in the power supply menu and the battery must be replaced.</p> <p>vBAT type: 1 pcs. Lithium CR 1220 3V</p>
<p>Replacement:</p> <ol style="list-style-type: none"> <li>1. The vBAT battery is located on the main PCB.</li> <li>2. Turn off 230 V mains and remove 20A backup battery fuse.</li> <li>3. Remove the main PCB plastic cover by unscrewing the 4 fixing screws</li> <li>4. Remove the button cell battery by inserting a small screwdriver in the right side of the vBAT. Press firmly to the left and lift.</li> <li>5. Insert the new battery with the plus side upwards, slide it in on the left side of the holder and press down. Put the plastic cover back.</li> <li>6. Reconnect all power supplies.</li> <li>7. Login in and go to "View all detail" – "system" menu and set time and date.</li> </ol>	<p>Location of vBAT</p>

## 22 Declaration of Conformity

The MotorControllers are manufactured and tested accordingly to the European requirements.

The total system is not to be put into service until a declaration of conformity for the total system has been made.

The "Declaration of Conformity" is supplied with MotorController as separate documents.