BACnet Protocol Implementation Conformance Statement

Date: 8 January 2026
Vendor Name: WindowMaster International A/S
Product Name: BACnet FlexiSmoke™
Product Model Number: WSA 5MC BACnet-IP
Firmware Revision: v1
BACnet Protocol Version: 1
BACnet Protocol Revision: 22

Product Description:

The WindowMaster WSA 5MC is a controller module used in WindowMaster's FlexiSmoke™ series of Smoke Control Panels (WSC 5xx). The WSA 5MC includes a network interface used for BACnet IP.

The WSC 5xx include an LCD with touch used to manipulate relevant device parameters such as BACnet Device ID's and UDP port number.

The WSC 5xx can be configured with different Motor Modules. The BACnet objects support the maximum configuration of 13 Motor Lines. For those Objects where Motor Modules are not present will the Object be indicated Out Of Service.

BACnet Standardized Device Profile (Annex L):

☐ BACnet Operator Workstation (B-OWS)
☐ BACnet Building Controller (B-BC)
☐ BACnet Advanced Application Controller (B-AAC)
☐ BACnet Application Specific Controller (B-ASC)
☐ BACnet Smart Sensor (B-SS)
☒BACnet Smart Actuator (B-SA)

BACnet Interoperability Building Blocks Supported (Annex K):

BIBB	Description
DS-RP-B	Data Sharing – ReadProperty - B
DS-RPM-B	Data Sharing – ReadPropertyMultiple - B
DS-WP-B	Data Sharing – WriteProperty - B
DS-COV-B	Data Sharing – Change of value – B
DM-DDB-B	Device Management – Dynamic Device Binding – B
DM-DOB-B	Device Management – Dynamic Object Binding – B

Segmentation Capability:

☐ Segmented requests supported Window Size _____
☒ Segmented responses supported Window Size 1 - 127

Standard Object Types Supported:
Object instantiation is static, i.e. objects cannot be created or deleted. Refer to table at end of this document for object details.

	Device	Analog			Binary			BitString
Property		**In**	**Out**	**Value**	**In**	**Out**	**Value**	**(In)**
Object Identifier	R	R	R	R	R	R	R	R
Object Name	R	R	R	R	R	R	R	R
Object Type	R	R	R	R	R	R	R	R
Description	R	R	R	R	R	R	R	R
System Status	R							
Vendor Name	R							
Vendor Identifier	R							
Model Name	R							
Firmware Revision	R							
Application Software Version	R							
Protocol Version	R							
Protocol Revision	R							
Protocol Services Supported	R							
Protocol Object Types Supported	R							
Object List	R							
Max APDU Length	R							
Segmentation Support	R							
APDU Timeout	R							
Number APDU Retries	R							
Device Address Binding	R							
Database Revision	R							
Active COV Subscriptions	R							
Present Value		R	W	W	R	W	W	R
Status Flags		R	R	R	R	R	R	R
Event State		R	R	R	R	R	R	R
Reliability		R		R	R			R
Out Of Service		R	R	R	R	R	R	R
Units		R	R	R				
Min Pres Value		R	R	R				
Max Pres Value		R	R	R				
Priority Array			R			R		
Relinquish Default			R			R		
COV Increments		R		R				
Polarity					R	R		
Inactive Text					R	R		
Active Text					R	R		
Bit Text								R

Analog Output Objects Instance Summary:

ID	Objects Name	Description	Unit	Present Value access
AO 1..13	Max_position_motor_group_1..13	Sets the maximum allowed position for motor group <n>	Percent	C
AO 14..26	Auto_position_motor_group_1..13	Sets the target position with auto speed for motor group <n>	Percent	C
AO 27..30	Max_position_motor_line_S3_X1..4	Sets the maximum allowed position for motor line S3 X<n>	Percent	C
AO 31..34	Max_position_motor_line_S4_X1..4	Sets the maximum allowed position for motor line S4 X<n>	Percent	C
AO 35..38	Max_position_motor_line_S5_X1..4	Sets the maximum allowed position for motor line S5 X<n>	Percent	C
AO 39	Max_position_motor_line_S1_X1	Sets the maximum allowed position for motor line S1 X1	Percent	C
AO 40..43	Auto_position_motor_line_S3_X1..4	Set the target position of motor line S3 X<n> using auto speed	Percent	C
AO 44..47	Auto_position_motor_line_S4_X1..4	Set the target position of motor line S4 X<n> using auto speed	Percent	C
AO 48..51	Auto_position_motor_line_S5_X1..4	Set the target position of motor line S5 X<n> using auto speed	Percent	C
AO 52	Auto_position_motor_line_S1_X1	Set the target position of motor line S1 X1 using auto speed	Percent	C
A0 53..65	Minimum_position_motor_group_1..13	Set the minimum position of motor group <n>	Percent	C
AO 66..69	Blind_slat_position_motor_line_S3_X1..4	Set the blind slat position of motor line S3 X<n>	Percent	C
AO 70..73	Blind_slat_position_motor_line_S4_X1..4	Set the blind slat position of motor line S4 X<n>	Percent	C
AO 74..77	Blind_slat_position_motor_line_S5_X1..4	Set the blind slat position of motor line S5 X<n>	Percent	C
AO 78	Blind_slat_position_motor_line_S1_X1	Set the blind slat position of motor line S1 X1	Percent	C

Analog Input Objects Instance Summary:

ID	Objects Name	Description	Unit	Present Value access
AI 1..4	Actual_position_motor_line_S3_X1..4	Contains the actual position for line S3 X<n>	Percent	R, COV
AI 5..8	Actual_position_motor_line_S4_X1..4	Contains the actual position for line S4 X<n>	Percent	R, COV
AI 9..12	Actual_position_motor_line_S5_X1..4	Contains the actual position for line S5 X<n>	Percent	R, COV
AI 13	Actual_position_motor_line_S1_X1	Contains the actual position for line S1 X1	Percent	R, COV
AI 14..17	Actual_max_position_motor_line_S3_X1..4	Contains the actual max position for motor line S3 X<n>	Percent	R, COV
AI 18..21	Actual_max_position_motor_line_S4_X1..4	Contains the actual max position for motor line S4 X<n>	Percent	R, COV
AI 22..25	Actual_max_position_motor_line_S5_X1..4	Contains the actual max position for motor line S5 X<n>	Percent	R, COV
AI 26	Actual_max_position_motor_line_S1_X1	Contains the actual max position for motor line S1 X1	Percent	R, COV
AI 27..39	Alarm_wind_direction_smoke_zone_1..13	Contains the actual alarm wind direction for smoke zone <n>		R, COV
AI 40	Building_mode	Contains the building mode		R, COV
AI 41..50	Temperature_in_NV_controller_1..10	Actual temperature in NV controller <n>	℃ / ℉	R, COV
AI 51..60	CO2_in_NV_controller_1..10	Actual CO_2 level in NV controller <n>	ppm	R, COV
AI 61..70	Relative_humidity_in_NV_controller_1..10	Actual relative humidity level in NV controller <n>	Percent	R, COV
AI 71..80	NV_actual_ventilation_temperature_setpoint_1..10	Actual ventilation temperature setpoint in NV controller <n>	℃ / ℉	R, COV
AI 81..90	NV_Actual_heating_temperature_setpoint_1..10	Actual heating temperature setpoint in NV controller <n>	℃ / ℉	R, COV
AI 91..100	NV_Ventilation_status_1..10	Actual ventilation status in NV controller <n>		R, COV
AI 101..110	NV_Comfort_status_1..10	Actual comfort status in NV controller <n>		R, COV
AI 111..120	Mech_vent_FutureVent_1..10	FutureVent™ control value		R, COV

ID	Objects Name	Description	Unit	Present Value access
AI 121..130	Mech_vent_value_1..10	Mechanical ventilation value	Percent	R, COV
AI 131..140	Mech_vent_ZoneVent_Air_supply_temperature_1..10	ZoneVent™ air supply temperature	℃ / ℉	R, COV
AI 141..150	Heating_Valve_1..10	Heating valve value	Percent	R, COV
AI 151	Weather_temperature	Weather station temperature	℃ / ℉	R, COV
AI 152	Weather_rain_intensity	Weather station rain intensity	mm/hour	R, COV
AI 153	Weather_relative_humidity	Weather station relative humidity	Percent	R, COV
AI 154	Weather_humidity	Weather station absolute humidity	g/m^3	R, COV
AI 155	Weather_dew_point	Weather station dew point	℃ / ℉	R, COV
AI 156	Weather_status_sensor	Weather station sensor status		R, COV
AI 157	Weather_wind_status	Weather status wind sensor status		R, COV
AI 158..167	Actual_temperature_setpoint_NV_controller_1..10	Actual temperature setpoint in NV controller <n>	℃ / ℉	R, COV
AO 168..171	Blind_actual_slat_position_motor_line_S3_X1..4	Contains the actual blind slat position of motor line S3 X<n>	Percent	R, COV
AO 172..175	Blind_actual_slat_position_motor_line_S4_X1..4	Contains the actual blind slat position of motor line S4 X<n>	Percent	R, COV
AO 176..179	Blind_actual_slat_position_motor_line_S5_X1..4	Contains the actual blind slat position of motor line S5 X<n>	Percent	R, COV
AO 180	Blind_actual_slat_position_motor_line_S1_X1	Contains the actual blind slat position of motor line S1 X1	Percent	R, COV
AI 181..190	Status_sunscreen_controller_1..10	Status of Sun controller <n>		R, COV
AI 191..200	Cooling_Valve_1..10	Cooling value for controller <n>	Percent	R, COV

Analog Value Objects Instance Summary:

ID	Objects Name	Description	Unit	Present Value access
AV 1..13	Hand_position_motor_group_1..13	Set the target position of motor group <n> using hand speed	Percent	W
AV14..26	Hand_relative_position_motor_group_1..13	Set the hand relative position for motor group <n>	Percent	W
AV 27..30	Hand_position_motor_line_S3_X1..4	Set the target position of motor line S3 X<n> using hand speed	Percent	W
AV 31..34	Hand_position_motor_line_S4_X1..4	Set the target position of motor line S4 X<n> using hand speed	Percent	W
AV 35..38	Hand_position_motor_line_S5_X1..4	Set the target position of motor line S5 X<n> using hand speed	Percent	W
AV 39	Hand_position_motor_line_S1_X1	Set the target position of motor line S1 X1 using hand speed	Percent	W
AV 40..43	Hand_relative_position_motor_line_S3_X1..4	Set the relative position of motor line S3 X<n> using hand speed	Percent	W
AV 44..47	Hand_relative_position_motor_line_S4_X1..4	Set the relative position of motor line S4 X<n> using hand speed	Percent	W
AV 48..51	Hand_relative_position_motor_line_S5_X1..4	Set the relative position of motor line S5 X<n> using hand speed	Percent	W
AV 52	Hand_relative_position_motor_line_S1_X1	Set the relative position of motor line S1 X1 using hand speed	Percent	W
AV 53	Wind_speed	Set the wind speed, used for safety	m/s	W
AV 54	Wind_speed_filtered	Set the filtered wind speed, used for NV	m/s	W
AV 55	Wind_direction	Set the wind direction	Degrees Angular	W
AV 56	Wind_direction_filtered	Set the filtered wind direction, used for NV	Degrees Angular	W
AV 57	Building_mode	Set the building mode		W
AV 58..67	Wind_speed_NV_controller_1..10	Set the wind speed in NV controller <n>, used for safety	m/s	W
AV 68..77	Wind_speed_filtered_NV_controller_1..10	Set the filtered wind speed in NV controller <n>, used for NV	m/s	W
AV 78..87	Temperature_NV_controller_1..10	Set the actual temperature in NV controller <n>	℃ / ℉	W
AV 88..97	CO2_NV_controller_1..10	Set the actual CO_2 level in NV controller <n>	Ppm	W
AV 98..107	Relative_humidity_NV_controller_1..10	Set the actual relative humidity in NV controller <n>	%	W
AV 108..117	Outdoor_temperature_in_NV_controller_1..10	Set the actual outdoor temperature used in NV controller <n>	℃ / ℉	W
AV 118..127	NV_base_temperature_setpoint_NV_controller_1..10	Set the base temperature setpoint in NV controller <n>	℃ / ℉	W
AV 128..137	NV_heating_cooling_deadband_NV_controller_1..10	Set the dead band between heating and cooling in NV controller <n>	K	W
AV 138..147	NV_heating_standby_offset_NV_controller_1..10	Sets the heating ‘standby’ offset in NV controller <n>	K	W
AV 148..157	NV_heating_night_offset_NV_controller_1..10	Sets the heating ‘night’ offset in NV controller <n>	K	W
AV 158..167	NV_cooling_standby_offset_NV_controller_1..10	Sets the cooling ‘standby’ offset in NV controller <n>	K	W
AV 168..177	NV_cooling_night_offset_NV_controller_1..10	Sets the cooling ‘night’ offset in NV controller <n>	K	W
AV 178..187	Mech_vent_temperature_setpoint_offset_1..10	Sets the mechanical ventilation setpoint in NV controller <n>	℃ / ℉	W
AV 188..191	Hand_timer_motor_line_S3_X1..4	Temporary hand timer for motor line S3 X<n>	Minutes	W
AV 192..195	Hand_timer_motor_line_S4_X1..4	Temporary hand timer for motor line S4 X<n>	Minutes	W
AV 196..199	Hand_timer_motor_line_S5_X1..4	Temporary hand timer for motor line S5 X<n>	Minutes	W
AV 200	Hand_timer_motor_line_S1_X1	Temporary hand timer for motor line S1 X1	Minutes	W
AV 201..210	Actual_illumination_sunscreen_controller_1..10	Set the illumination level in sun controller <n>		W

Binary Output Objects Instance Summary:

ID	Objects Name	Description	Active / inactive Text	Present Value access
BO 1..4	Close_motor_line_S3_X1..4	Set that motor line S3 X<n> must be closed	Close. All motors on the motor line must be closed / No close	C
BO 5..8	Close_motor_line_S4_X1..4	Set that motor line S4 X<n> must be closed	Close. All motors on the motor line must be closed / No close	C
BO 9..12	Close_motor_line_S5_X1..4	Set that motor line S5 X<n> must be closed	Close. All motors on the motor line must be closed / No close	C
BO 13	Close_motor_line_S1_X1	Set that motor line S1 X1 must be closed	Close. All motors on the motor line must be closed / No close	C
BO 14..23	NV_Presence_detection_1..10	Set a presence detection event in NV controller <n>.	Idle. No presence detection. / Presence detection. Trigger the occupancy timer.	C
BO 24..33	NV_Disable_automatic_1..10	Set that automatic control is disabled in NV controller <n>	Idle. / Disable auto. NV control. Disable the NV controller.	C
BO 34..43	NV_Force_winter_1..10	Set that NV controller <n> is force in winter mode	Idle. / Force winter. Force the NV controller in winter mode.	C
BO 44..53	NV_Ventilate_1..10	Set that a pulse ventilation must be performed in NV controller <n>	Idle. / Ventilate trigger. Trigger a ventilation sequence in the NV controller.	C
BO 54..63	NV_Comfort_1..10	Set that ‘comfort’ must be active used in NV controller <n>	Idle. / Comfort. Set the NV controller in comfort mode.	C
BO 64..73	NV_Night_1..10	Set that ‘night’ must be active used in NV controller <n>	Idle. / Night. Set the NV controller in night mode.	C
BO 74..83	Mech_vent_override_1..10	Set override in mechanical ventilation controller <n>	Idle. / Mech. vent. override. Set the mech. vent. controller in override mode to manually set the output.	C
BO 84..93	Heating_override_1..10	Set override in heating controller <n>	Idle. / Heating override. Set the heating controller in override mode to manually set the heating output.	C
BO 94…103	Cooling_override_1..10	Set override in cooling controller <n>	Idle. / Cooling override. Set the cooling controller in override mode to manually set the cooling output.	

Binary Input Objects Instance Summary:

ID	Objects Name	Description	Active / inactive Text	Present Value access
BI 1..4	Closed_motor_line_S3_X1..4	Indicates closed / not closed status for actuators on motor line S3 X<n>	Closed. All motors on the motor line are closed / Not closed. One or more motors on the motor line are open	R, COV
BI 5..8	Closed_motor_line_S4_X1..4	Indicates closed / not closed status for actuators on motor line S4 X<n>	Closed. All motors on the motor line are closed / Not closed. One or more motors on the motor line are open	R, COV
BI 9..12	Closed_motor_line_S5_X1..4	Indicates closed / not closed status for actuators on motor line S5 X<n>	Closed. All motors on the motor line are closed / Not closed. One or more motors on the motor line are open	R, COV
BI 13	Closed_motor_line_S1_X1	Indicates closed / not closed status for actuators on motor line S1 X1	Closed. All motors on the motor line are closed / Not closed. One or more motors on the motor line are open	R, COV
BI 14..17	Error_motor_line_S3_X1..4	Indicates error condition for motor line S3 X<n>	Error. An error was detected on the motor line / No error. No errors detected on the motor line	R, COV
BI 18..21	Error_motor_line_S4_X1..4	Indicates error condition for motor line S4 X<n>	Error. An error was detected on the motor line / No error. No errors detected on the motor line	R, COV
BI 22..25	Error_motor_line_S5_X1..4	Indicates error condition for motor line S5 X<n>	Error. An error was detected on the motor line / No error. No errors detected on the motor line	R, COV
BI 26	Error_motor_line_S1_X1	Indicates error condition for motor line S1 X1	Error. An error was detected on the motor line / No error. No errors detected on the motor line	R, COV
BI 27..39	Alarm_smoke_zone_1..10	Smoke zone <n> alarm condition.	Alarm active in the smoke zone / No alarm active in the smoke zone	R, COV
BI 39..52	Error_smoke_zone_1..10	Smoke zone <n> error	Error. An error was detected on the smoke zone / No error. No errors detected on the smoke zone	R, COV
BI 43	Error_system	System error status	System error. One or more error in the system / System ok. No errors active in the system	R, COV
BI 54	Error_nv_controllers	One or more NV controllers has an error	System ok. No NV controllers with error. / NV controller error. At least one NV controller has an error.	R, COV
BI 55	Common_mech_vent	Mechanical ventilation is active in one or more NV controllers	Mech. vent. inactive. No mech. vent. controller has an active output. / Mech. vent. active. One or more mech. vent. controllers have an active output.	R, COV
BI 56	Common_heating	Heating is active in one or more NV controllers	Heating inactive. No heating controller has heating demand. / Heating active. One or more heating controller has heating demand.	R, COV
BI 57..66	NV_Occupancy_1..10	NV controller <n> is occupied	Unoccupied. The NV controller is unoccupied. / Occupied. The NV controller is occupied.	R, COV
BI 67..76	NV_Winter_1..10	NV controller <n> is in winter mode	Summer. The NV controller is in summer mode. / Winter. The NV controller is in winter mode.	R, COV
BI 77..86	NV_Lighting_1..10	The light is on in NV controller <n>	Lighting off. The NV controller has lighting off. / Lighting on. The NV controller has lighting on.	R, COV
BI 87..96	NV_Error_status_1..10	NV controller <n> has an error	OK. No errors in the NV controller. / Error. The NV controller has an error.	R, COV
BI 97..106	Mech_vent_1..10	The mechanical ventilation is active in mechanical ventilation controller <n>	Mech. vent. inactive. The mech. vent. controller output is not active. / Mech. vent. active. The mech. vent. controller has an active output.	R, COV

ID	Objects Name	Description	Active / inactive Text	Present Value access
BI 107..116	Heating_1..10	The heating is active in heating controller <n>	Heating inactive. The heating controller output is not active. / Heating active. The heating controller has an active output.	R, COV
BI 117	Weather_raining	Raining signal from weather station	No rain. The rain sensor is not active. / Raining. The rain sensor is active.	R, COV
BI 118…127	Cooling_1..10	The cooling is active in cooling controller <n>	Cooling inactive. The cooling controller output is not active. / Cooling active. The cooling controller has an active output.	R, COV

Binary Value Objects Instance Summary:

ID	Objects Name	Description	Active / inactive Text	Present Value Access
BV 1..13	Connection_1..13	Object that can be associated to an input or output of the system		R/W

Bit String Value Objects Instance Summary:

ID	Objects Name	Description	Bit_Text	Present Value access
BS 1..13	Status_motor_group_1..13	Indicate status of the motor group <n>	Bit 0: 1 = Error. One or more motor lines associated with the motor groups have an error. Bit 1: 1 = Closed. All motor lines associated with the motor group is closed. Bit 2: 1 = Max. wind speed active. The configured max. wind speed of the motor group is exceeded. Bit 3: 1 = Safety active. The safety function of the motor group is active. Bit 4: 1 = Open active. One or more motor lines in the group are open more than the configured threshold. Bit 5: 1 = Alarm. The motor group is in smoke alarm state. Bit 6: 1 = Service. One or more motor lines calls for service. Bit 7: 1 = KNX error. The KNX module or bus has an error.	R
BS 14..17	Status_motor_line_S3_X1..4	Indicate status for motor line S3 X<n>	Bit 0: 1 = Communication error. Communication error detected while communicating with one or more motors. Only applicable for MotorLink™ output. Bit 1: 1 = Cable error. Broken cable detected. Only applicable for standard motor output. Bit 2: 1 = No. of. motors error. Expected no. of motors differs from the number of motors found on the motor line. Bit 3: 1 = Team size error. Team size value in the motors does not match. Bit 4: 1 = Motor parameter error. Key motor parameters differ between the motors. Bit 5: 1 = No. of locking motors error. Expected no of WMB motors differ from number found. Bit 6: 1 = Locking motors team size error. Team size value in the locking motors does not match. Bit 7: 1 = Locking motor parameter error. Key locking motor parameters differs between the locking motors. Bit 8: 1 = Closed. All actuators on motor line are closed. Bit 9: 1 = Locked. All locking motors are locked. If no locking motors are present the bit has the same value as "Closed". Bit 10: 1 = Position error. The actual position differs from the expected position. Bit 11: 1 = Motor moving. Motors are moving. Bit 12: 1 = Motor over current. The motors reported a too high current. Bit 13: 1 = Output over current. A too high current detected on the motor line output. Bit 14: 1 = Hand grace timer active. An automatic operation has started the grace timer. Bit 15: 1 = Hand timer active. A hand operation has started the temporary hand timer. Bit 16: 1 = Power supply overcurrent. Accumulator switch opened due to overcurrent. Bit 17: 1 = Motor safety edge sensor input active.	R
BS 18..21	Status_motor_line_S4_X1..4	Indicate status for motor line S4 X<n>	Please see BS 14	R
BS 22..25	Status_motor_line_S5_X1..4	Indicate status for motor line S5 X<n>	Please see BS 14	R
BS 26	Status_motor_line_S1_X1	Indicate status for motor line S1 X1	Please see BS 14	R

ID	Objects Name	Description	Bit_Text	Present Value access
BS 27..39	Status_smoke_zone_1..13	Indicate status of smoke zone <n>	Bit 0: 1 = Line A alarm active. Bit 1: 1 = Line B alarm active. Bit 2: 1 = Reset active. Bit 3: 1 = Line C alarm active. Bit 4: 1 = Line D alarm active. Bit 5: 1 = Line E alarm active. Bit 6: 1 = Line F alarm active. Bit 7: 1 = Line A error. Bit 8: 1 = Line B error. Bit 9: 1 = Line C error. Bit 10: 1 = Line D error. Bit 11: 1 = Line E error. Bit 12: 1 = Line F error. Bit 13: 1 = Break glass unit error. Error affecting the break glass units associated with the smoke zone. Bit 14: 1 = Motor group error. Error effecting the motor groups associated with the smoke zone. Bit 15: 1 = Master / slave error. Error effecting a master or slave connection on the smoke zone. Bit 16: 1 = Power supply error. No mains power or PS module error. Bit 17: 1 = Mains power warning. Mains power has been missing for less than (*) minutes. Bit 18: 1 = Weather data error.	R
BS 40	Status_system	Indicates the detailed status of the system.	Bit 0: 1 = Alarm. Alarm is active in one or more smoke zone. Bit 1: 1 = System error. Errors active in the system. Bit 2: 1 = Mains error. Mains power is ok. The first (*) min. of a mains failure is shown as a warning. Bit 3: 1 = Mains warning. Mains power failure for less than (*) minutes. Bit 4: 1 = Accumulator error. An accumulator error is detected. Bit 5: 1 = Weather data error. Bit 6: 1 = Time for service. The system maintenance timer has expired.	R

(*) is the value of parameter 1.9.0.38 “Mains error time”.

Present Value Access types Legend: R = Read-only, W (Note1) = Writeable, C = Commandable. Commandable values supports priority arrays 16 relinquish defaults.

Data Link Layer Options:

☒ BACnet IP, (Annex J)
☐ BACnet IP, (Annex J), Foreign Device
☐ ISO 8802-3, Ethernet (Clause 7)
☐ ANSI/ATA 878.1, 2.5 Mb. ARCNET (Clause 8)
☐ ANSI/ATA 878.1, RS-485 ARCNET (Clause 8), baud rate(s): _____
☐ MS/TP master (Clause 9), baud rate(s): _____
☐ MS/TP slave (Clause 9), baud rate(s): _____
☐ Point-To-Point, EIA 232 (Clause 10), baud rate(s):_____
☐ Point-To-Point, modem, (Clause 10), baud rate(s): _____
☐ LonTalk, (Clause 11), medium: _____
☐ Other: _____

Device Address Binding:

Is static device binding supported? (This is currently necessary for two-way communication with MS/TP slaves and certain other devices.) ☐Yes ☒ No

Networking Options:

☐ Router, Clause 6 - List all routing configurations, e.g., ARCNET-Ethernet, Ethernet-MS/TP, etc.
☐ Annex H, BACnet Tunnelling Router over IP
☐ BACnet/IP Broadcast Management Device (BBMD)
Does the BBMD support registrations by Foreign Devices? ☐ Yes ☐ No

Character Sets Supported:

Indicating support for multiple character sets does not imply that they can all be supported simultaneously.

☒ ISO 10646 (UTF-8)	☐ IBM™/Microsoft™ DBCS	☐ ISO 8859-1
☐ ISO 10646 (UCS-2)	☐ ISO 10646 (UCS-4)	☐ JIS C 6226